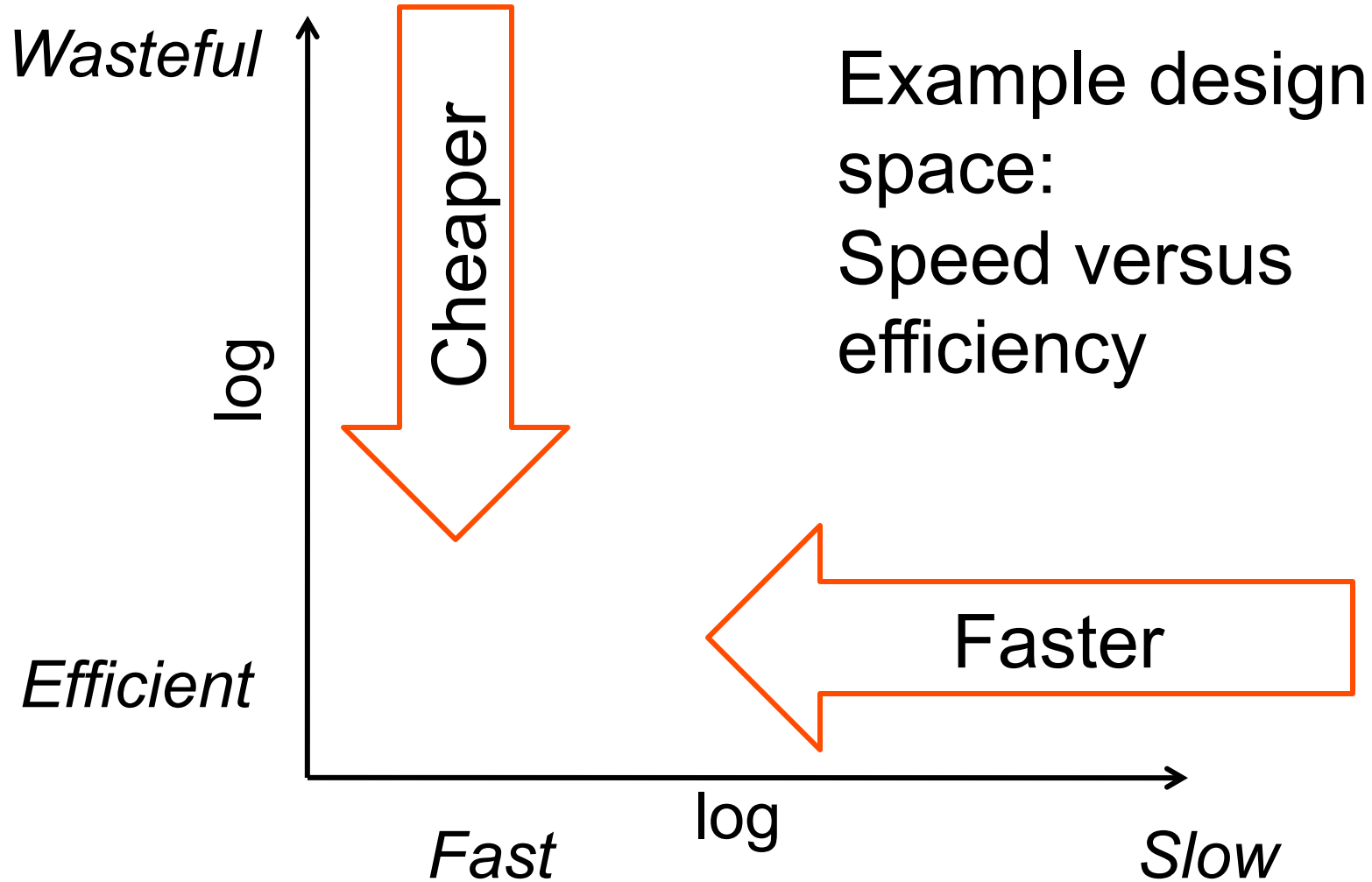
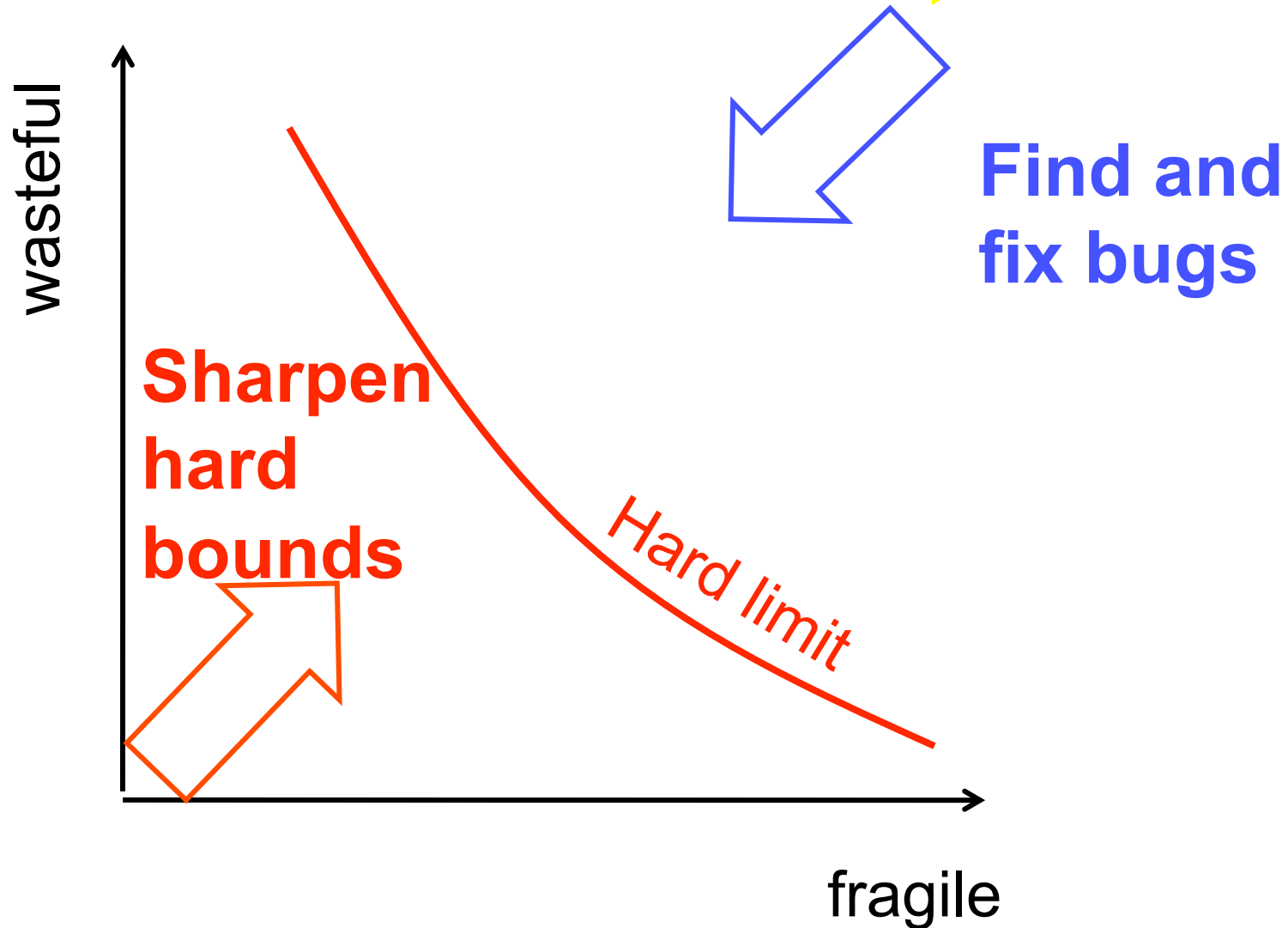


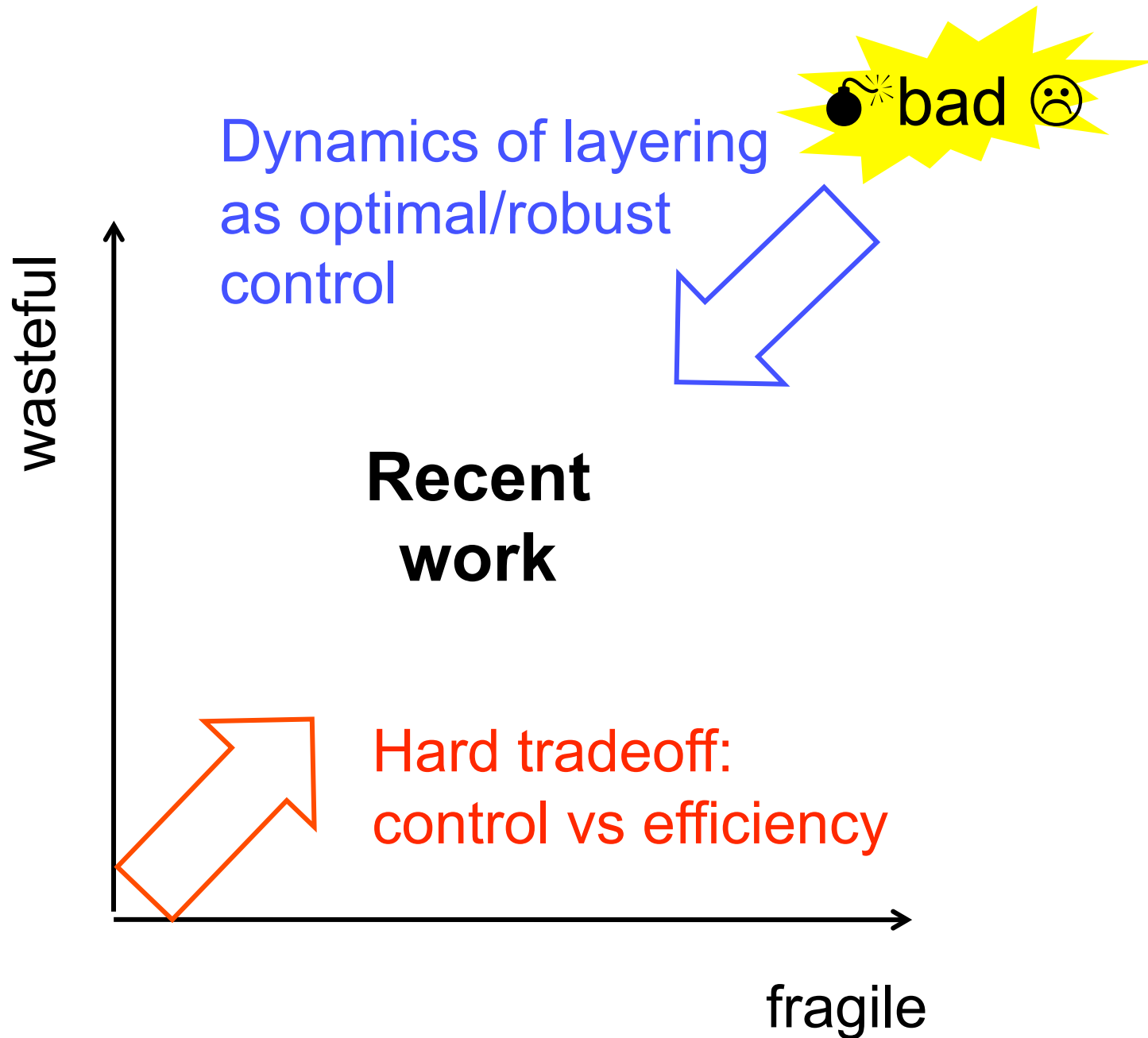
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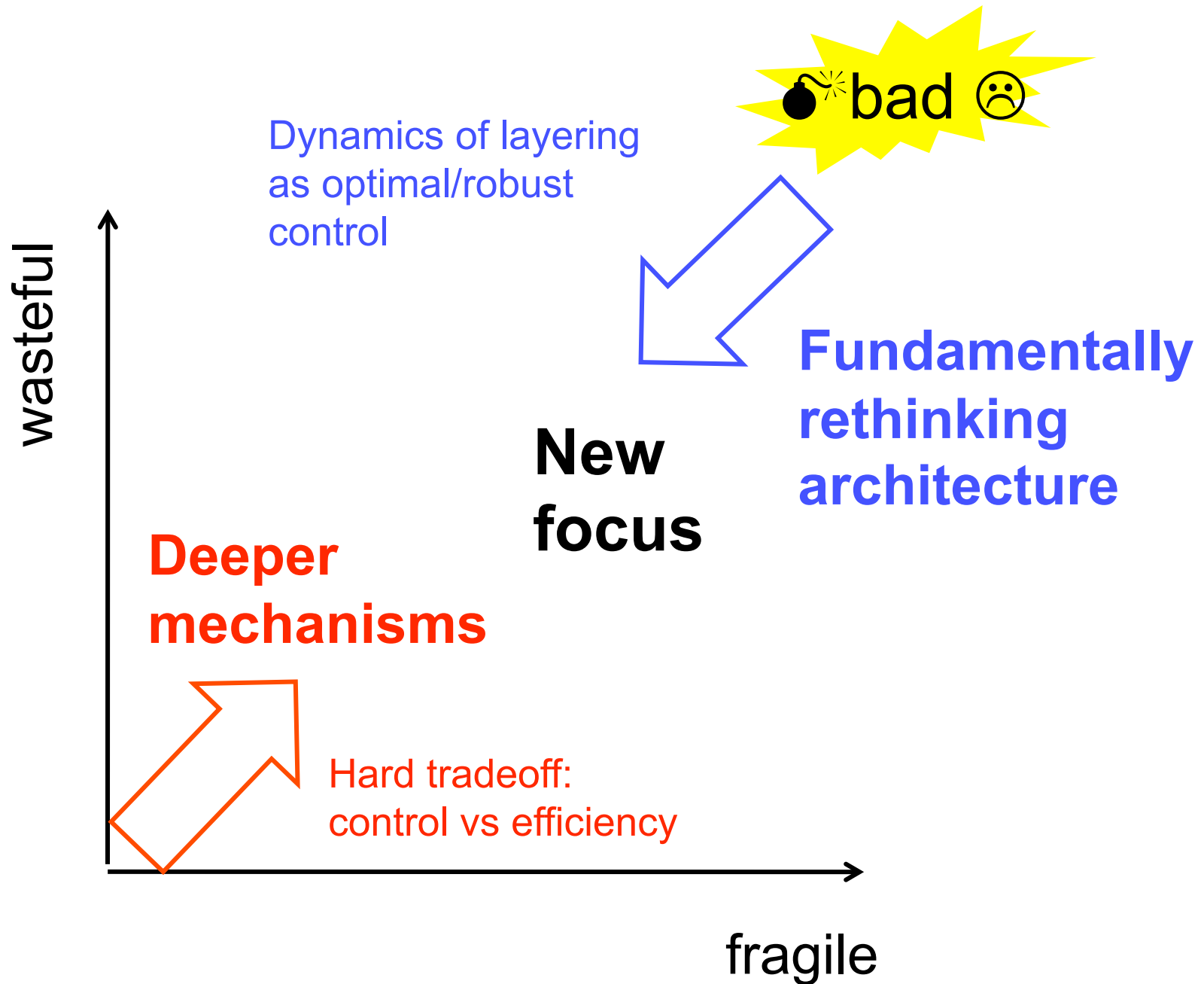
# Design tradeoffs



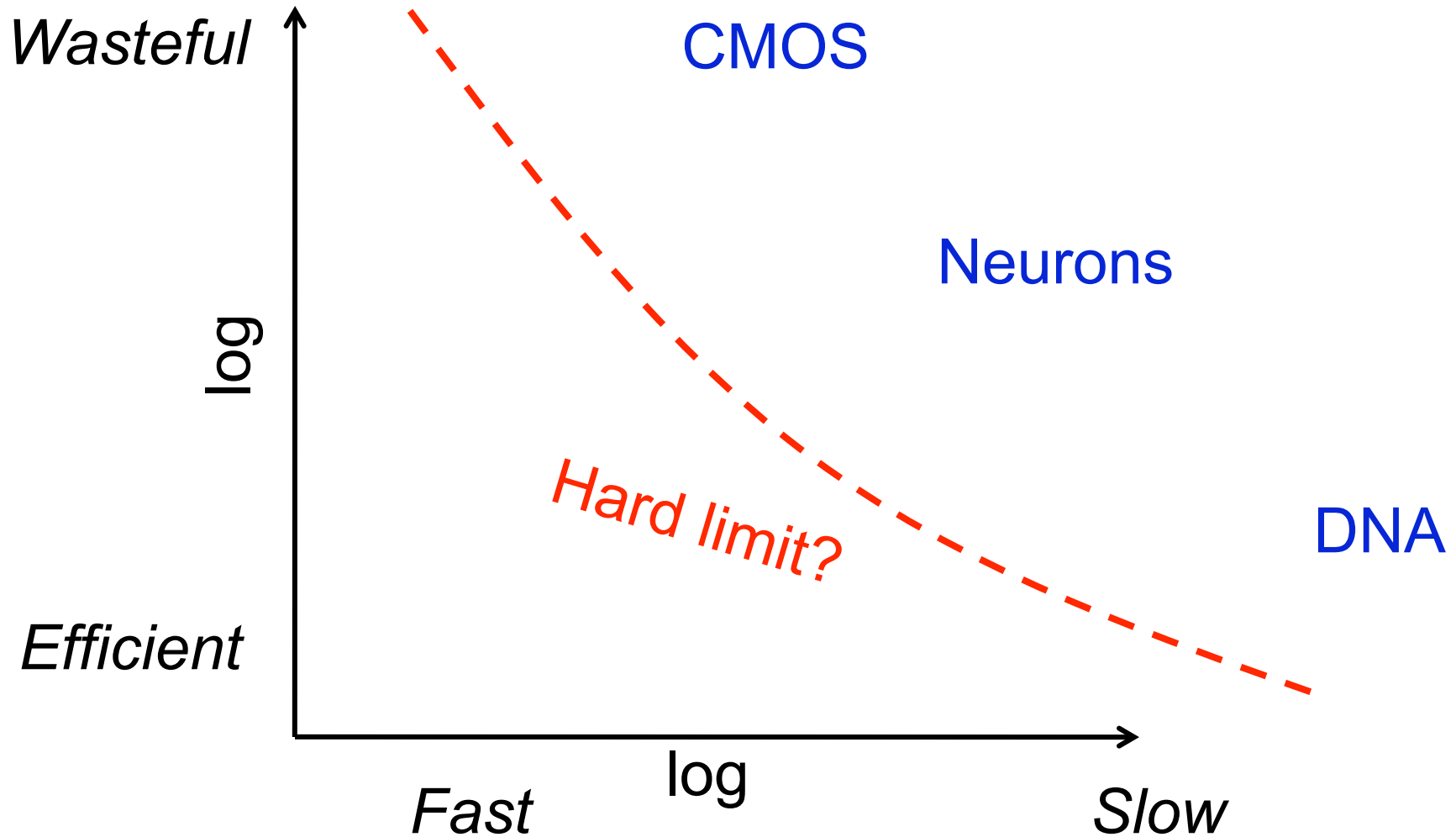
# Complementary approaches





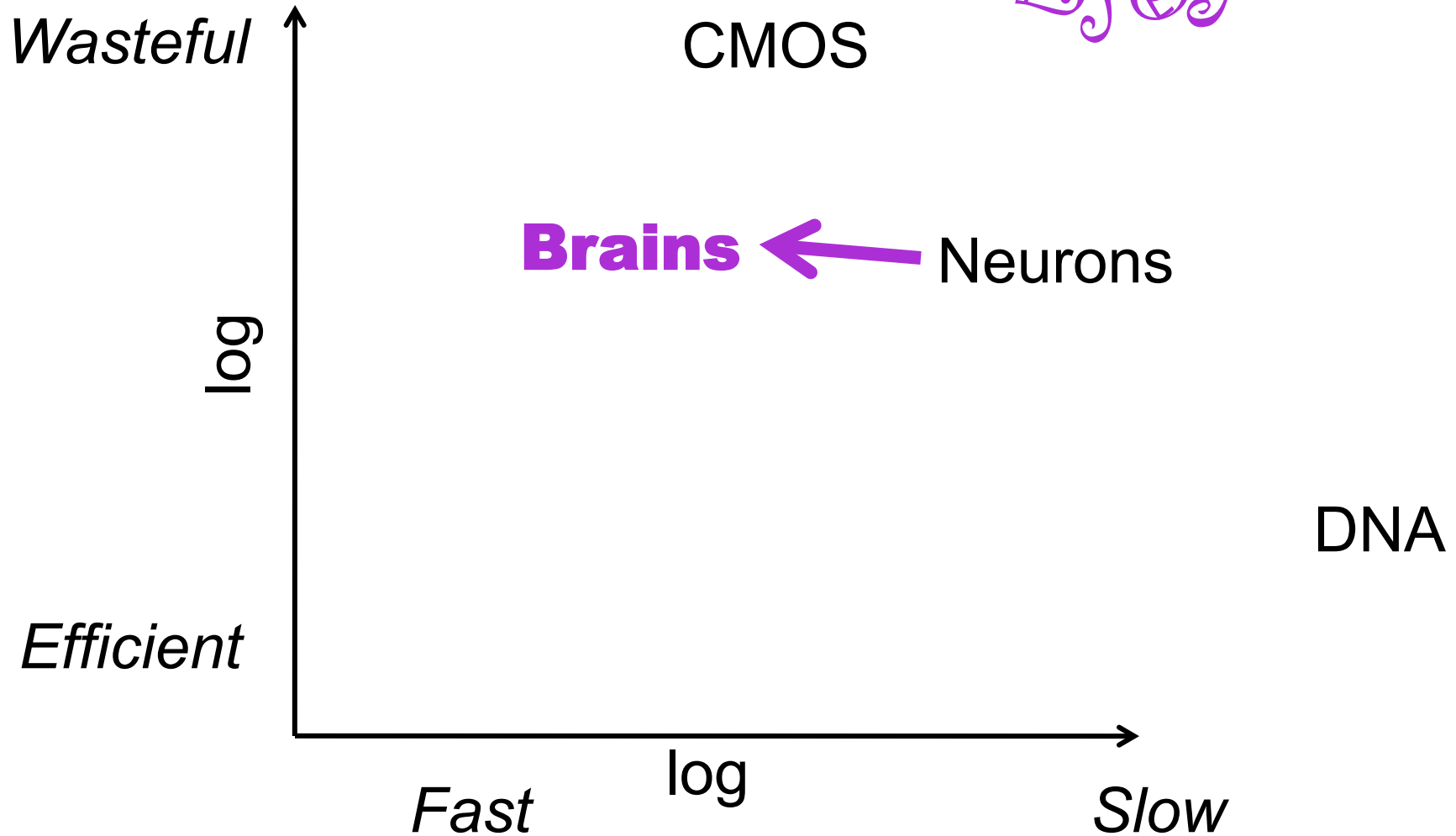


# Computational hardware substrates

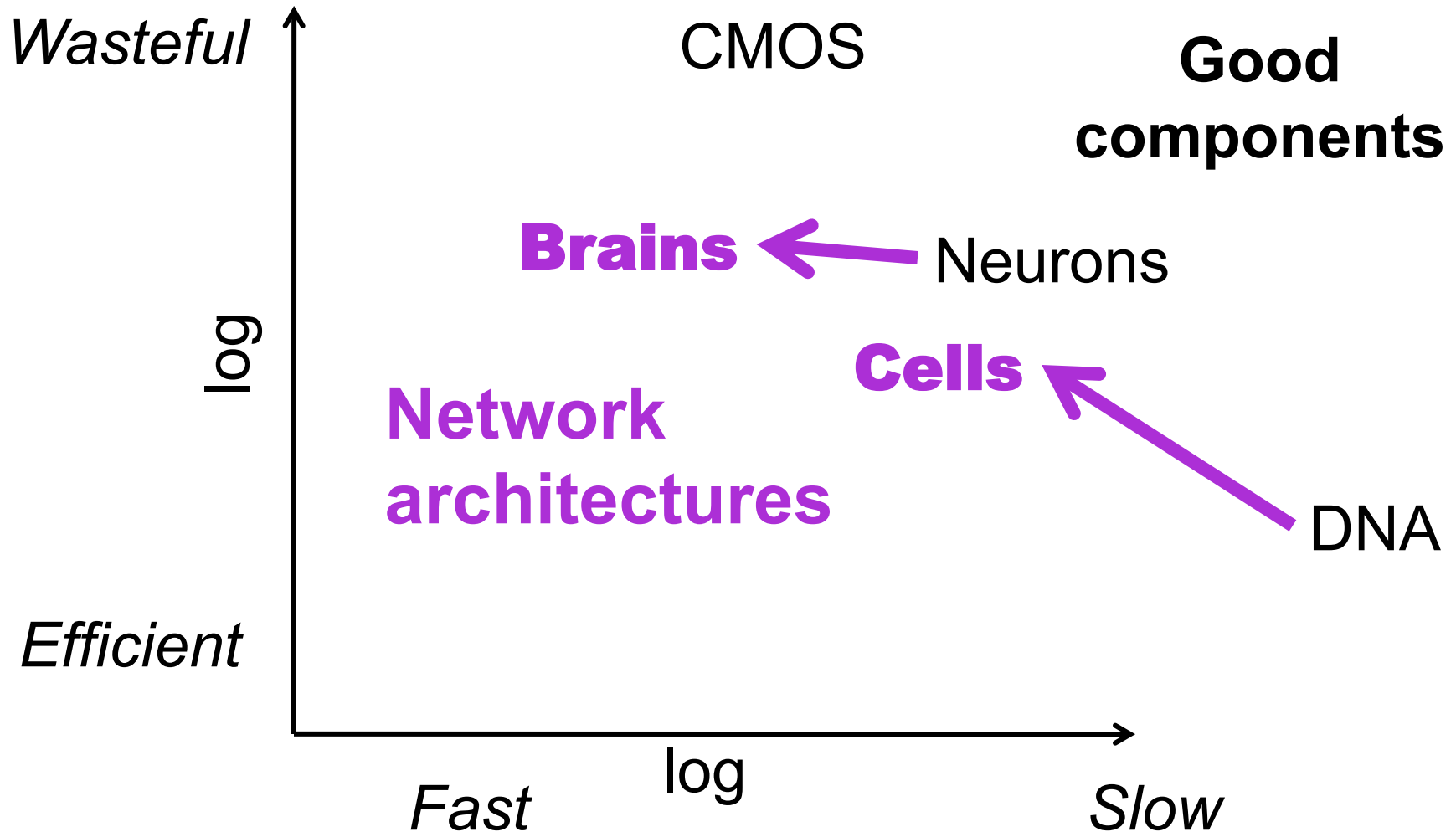


Some tasks: ~~HARD~~ HARD for computers

~~EASY~~ EASY for us



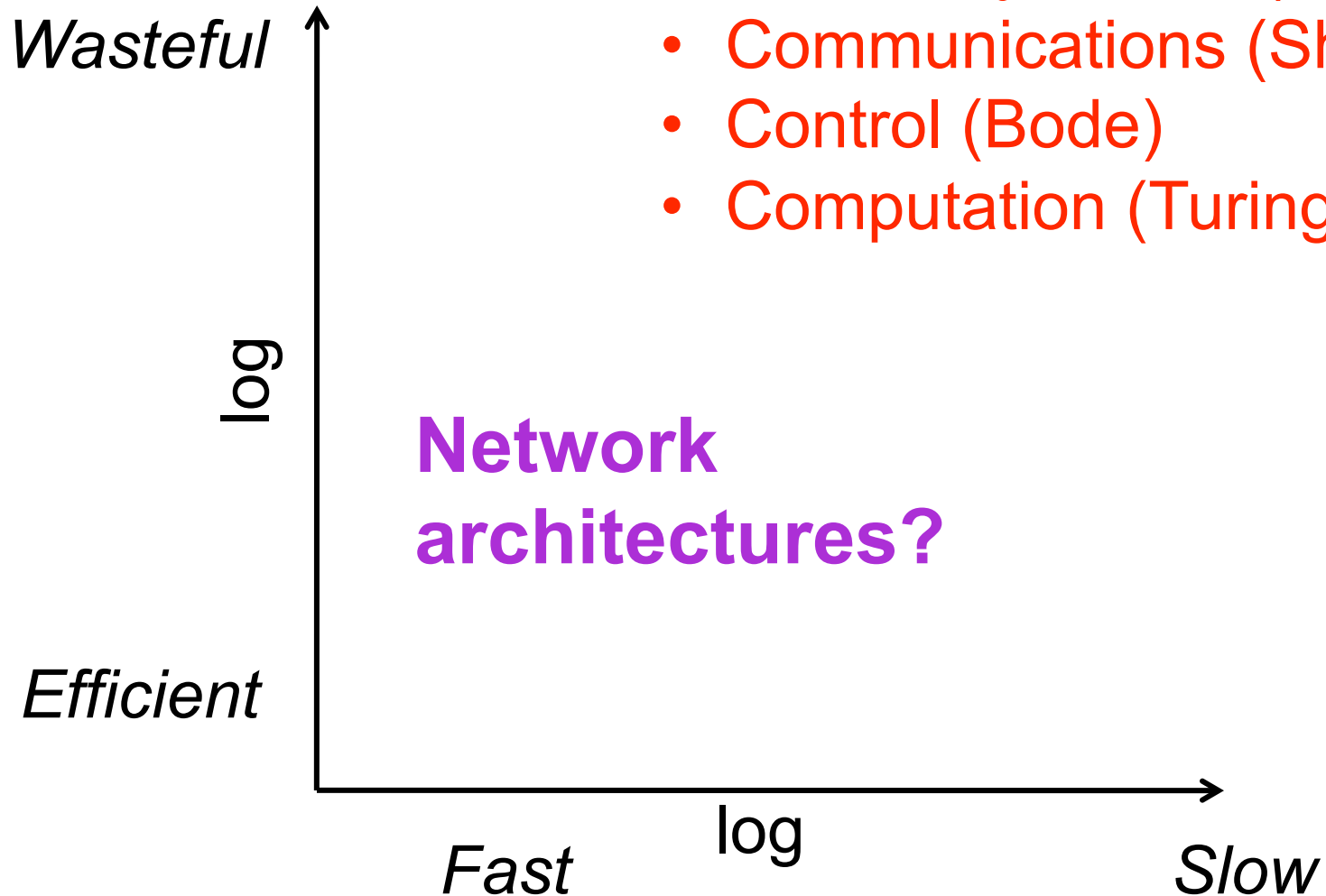
# What makes this possible?





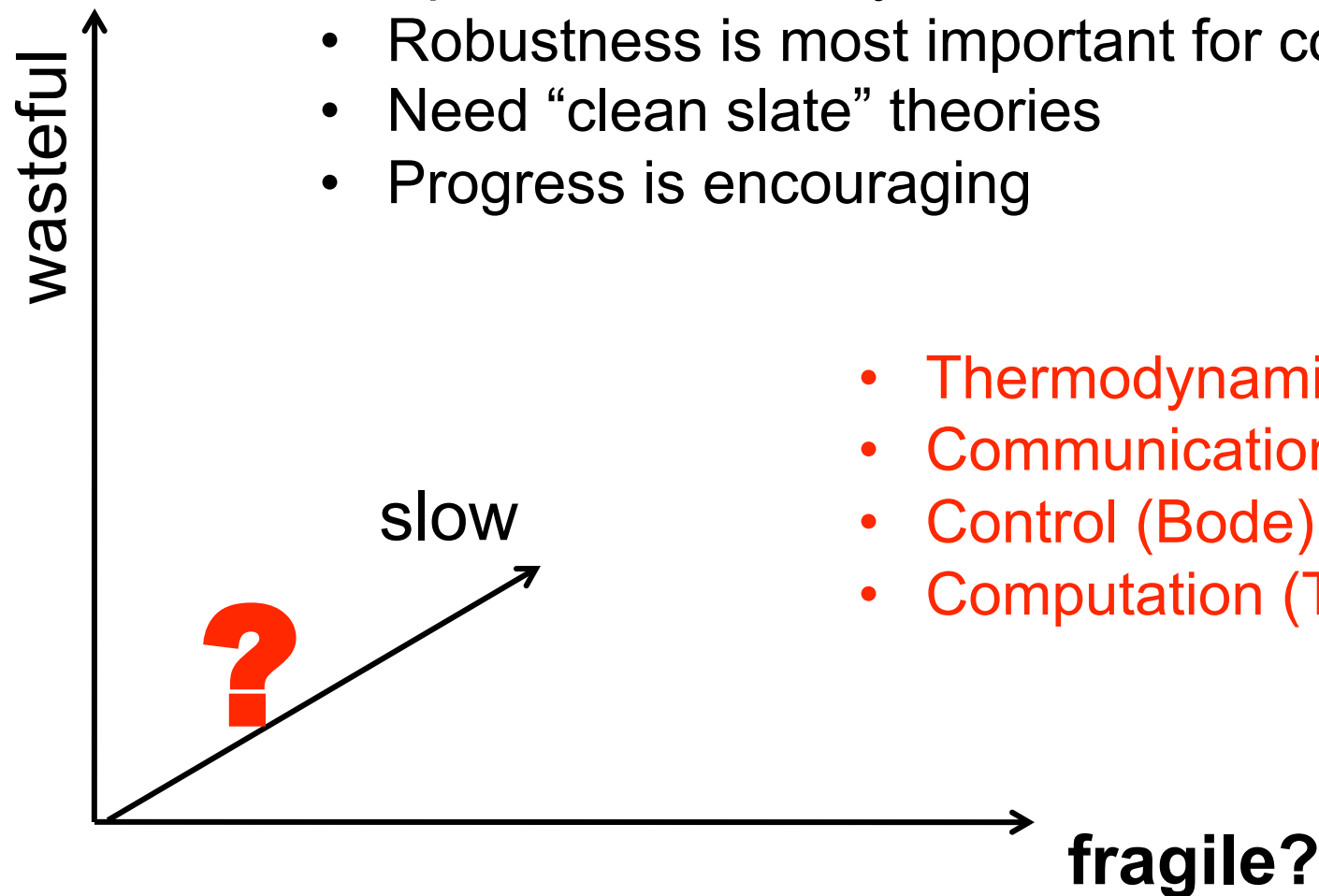
Standard theories are severely limited

- Thermodynamics (Carnot)
- Communications (Shannon)
- Control (Bode)
- Computation (Turing)



## Standard theories are severely limited

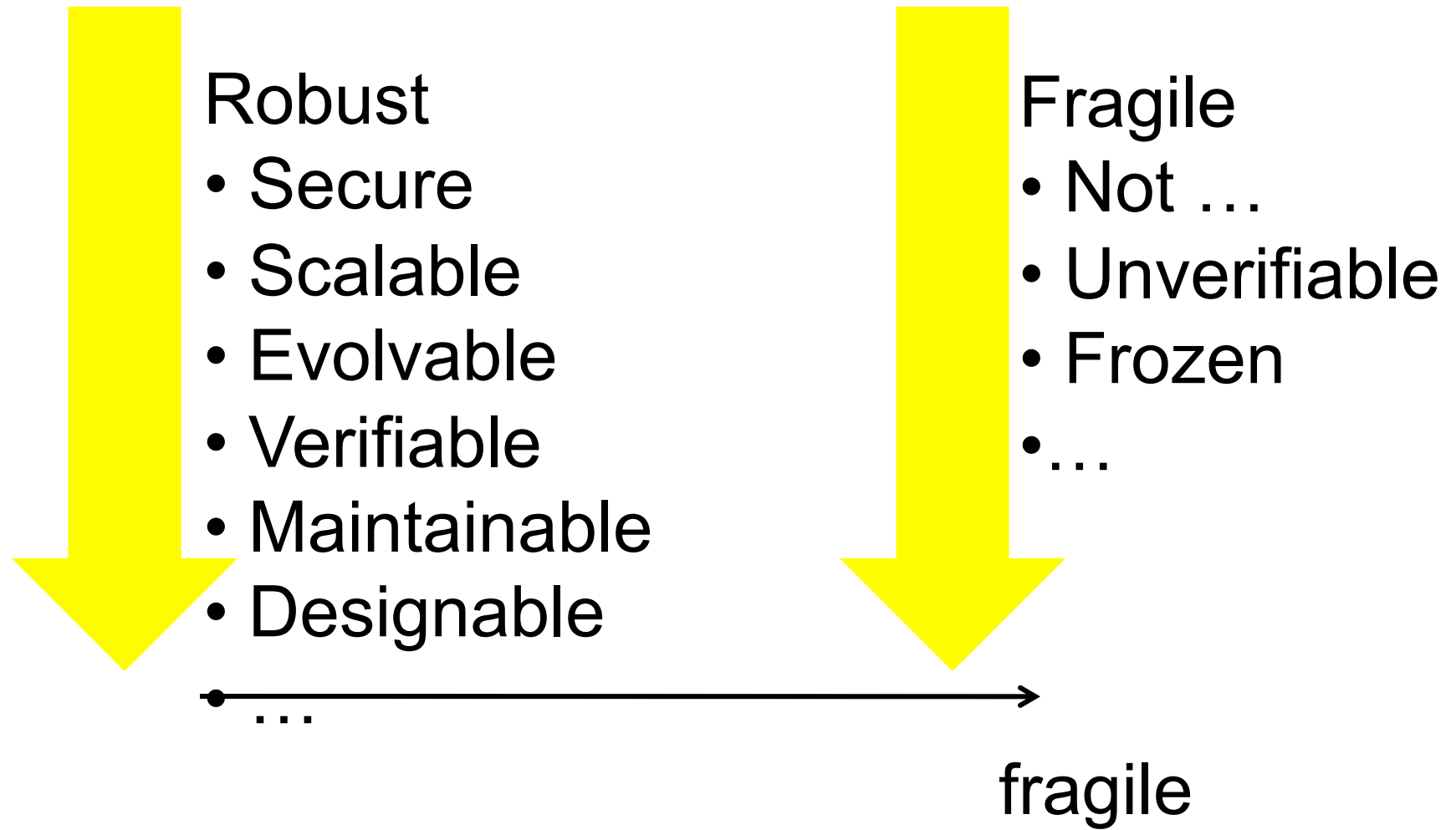
- Each focuses on few dimensions
- Important tradeoffs are **across** these dimensions
- Speed vs efficiency vs robustness vs ...
- Robustness is most important for complexity
- Need “clean slate” theories
- Progress is encouraging



- Thermodynamics (Carnot)
- Communications (Shannon)
- Control (Bode)
- Computation (Turing)

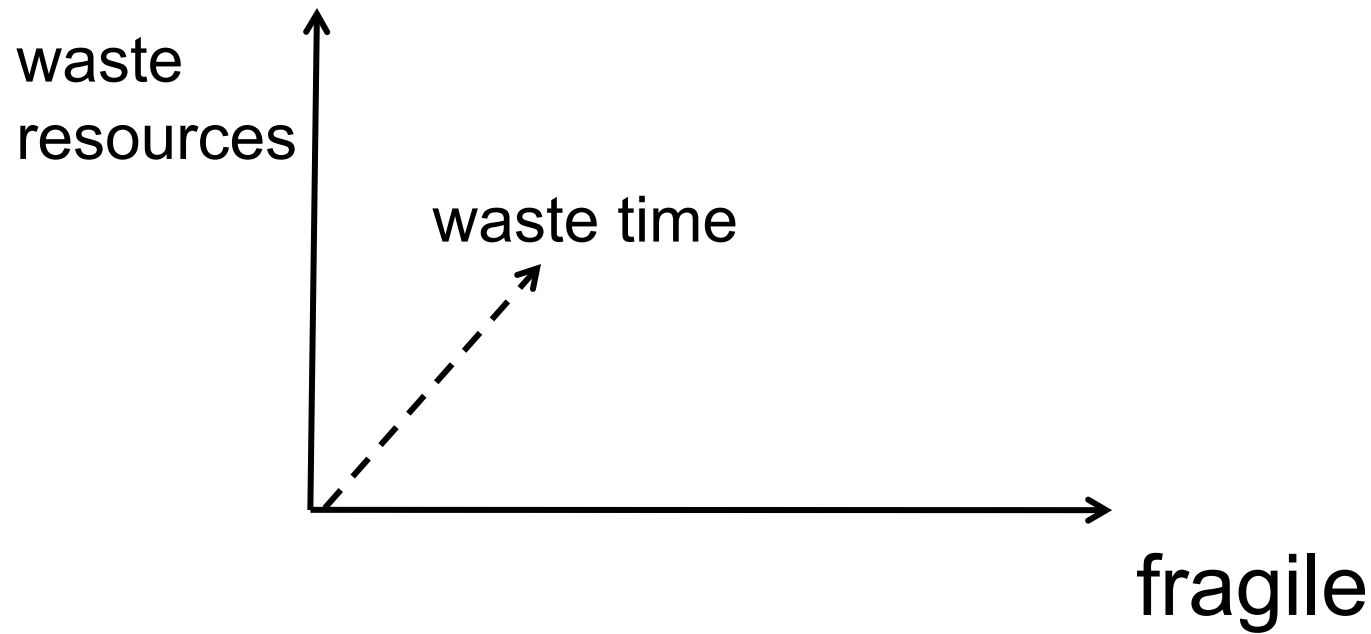
# Most dimensions are robustness

## Collapse for visualization



- Important tradeoffs are **across** these dimensions
- Speed vs efficiency vs robustness vs ...
- Robustness is most important for complexity
- Collapse efficiency dimensions

wasteful



- Important tradeoffs are ***across*** these dimensions
- Speed vs efficiency vs robustness vs ...
- Robustness is most important for complexity
- Collapse efficiency dimensions

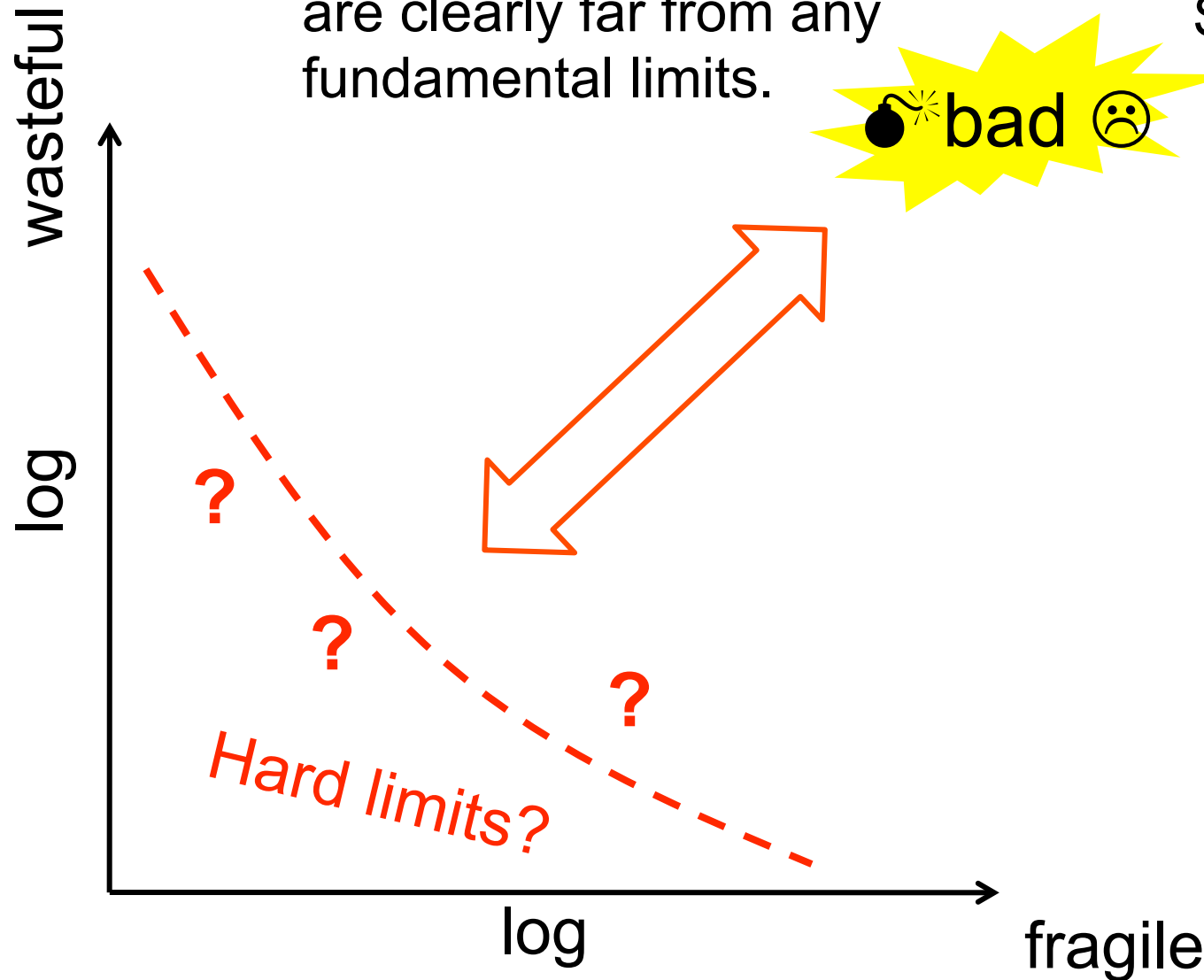
wasteful



fragile

But many existing systems and architectures are clearly far from any fundamental limits.

So fixing “bugs” in existing architectures has most immediate impact.



Note: “log” suggests orders of magnitude variations

# Important Influences

- There increasingly many researchers/authors with increasingly coherent thinking about architecture
- Remarkably convergence across many fields
- Different language and domains so translation is difficult

## New (and old) connections

- **Biology/Medicine** (Savageau, G&K, Mattick, Csete, Arkin, Alon, Caporale, de Duve, Exerc Physio, Acute Care, etc...)
- **Internet** (Kelly/Low, Willinger, Chang, Clark, Wroclawski, Alderson, Day, etc)
- **Management** (Baldwin,...)
- **Resilience/Safety/Security Engineering/Economics** (Wood, Anderson, ...)
- **Platform Based Design**: Alberto S-V, Lee, ...



## Other Complex Influences

- **Architecture** (Alexander, Salingeros,...)
- **Aerospace** (many, Maier is a good book)
- **Philosophy/History** (Fox Keller, Jablonka&Lamb)
- **Physics/ecology** (Carlson)

## First emphasis (+new)

- Internet (Day, Low, Willinger, Clark, Wroclawski,...)
- Statistical mechanics (Sandberg, Delvenne,...)
- Biology (lots...)

Other topics maybe later:

- Antennas and beam forming (Lavaei, Babakhani, Hajimiri)
- Shear flow turbulence (Gayme, McKeon, Bamieh)

# Modern theory and the Internet









## Levels of understanding

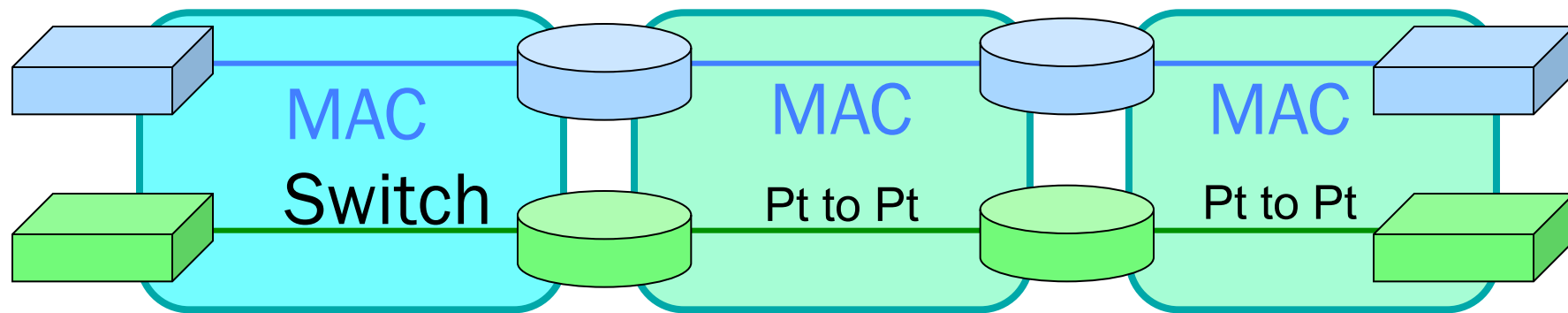
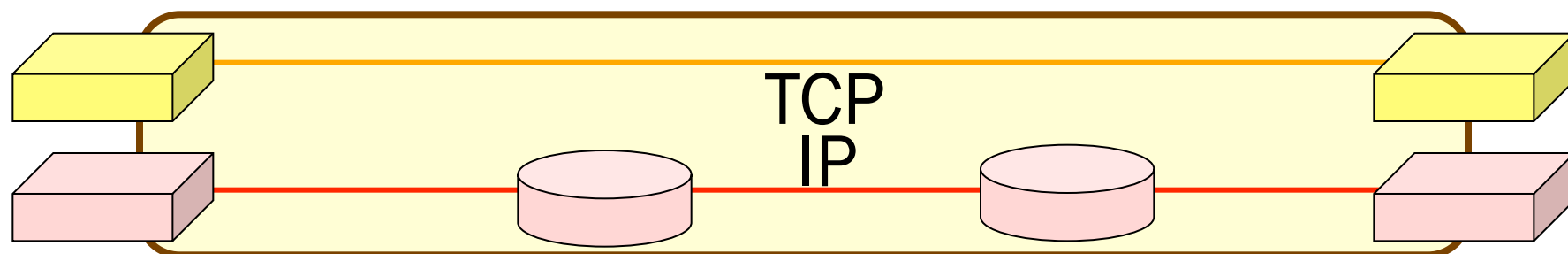
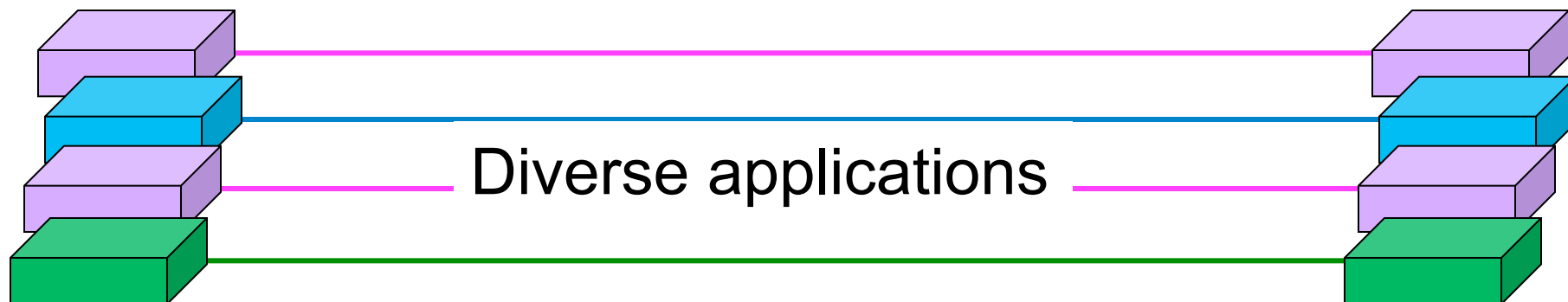
Verbal/cartoon
Data and statistics
Modeling and simulation
Analysis
Synthesis

## Topics

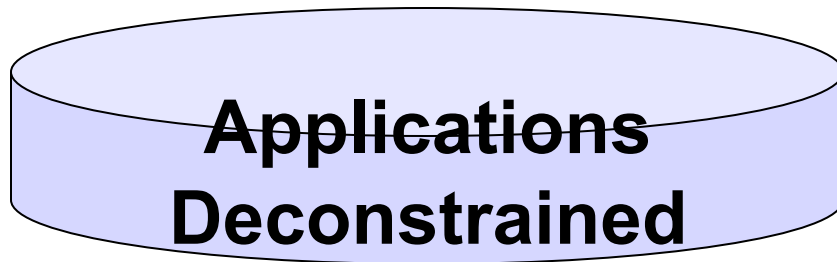
Traffic
Topology
Control and dynamics
Layering
Architecture

# Recent progress (1995-)

	Traffic	Topology	C&D	Layering	Architect.
Cartoon					?
Data/stat					
Mod/sim					
Analysis					
Synthesis					



# Theoretical framework: Constraints that deconstrain



$$\min_{\mathbf{x}} \left\{ \int \left( \|R\tilde{\mathbf{x}} - \mathbf{c}\|^2 + \|R\mathbf{x} - \mathbf{c}\|^2 \right) dt \right\}$$
$$\left| \begin{array}{l} \tilde{\mathbf{x}} = \arg \max_{\mathbf{v}} L(\mathbf{v}, \mathbf{p}), \quad \dot{\mathbf{p}} = R\mathbf{x} - \mathbf{c} \\ \Rightarrow x_s = \arg \max_{\mathbf{v}} L_s(\mathbf{v}, \mathbf{p}) \end{array} \right.$$



Enormous progress

- Layering
- Optimization
- Optimal control
- Robust control
- Game theory
- Network coding

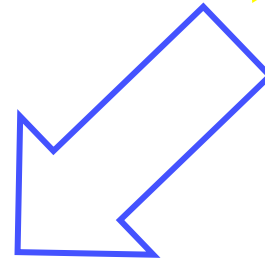
Continuing progress  
but clear limitations.

# Theoretical framework: Constraints that deconstrain

## Enormous progress

- Layering
- Optimization
- Optimal control
- Robust control
- Game theory
- Network coding

- Many robustness issues left unaddressed
  - Secure, verifiable, manageable, maintainable, etc
  - Architecture/policy, not part of control/dynamics
  - How to expand the theory?
  - What are obvious bugs?
- 
- Note: Huge success of TCP/IP may have blinded us to historical artifacts, need theory-based rethinking



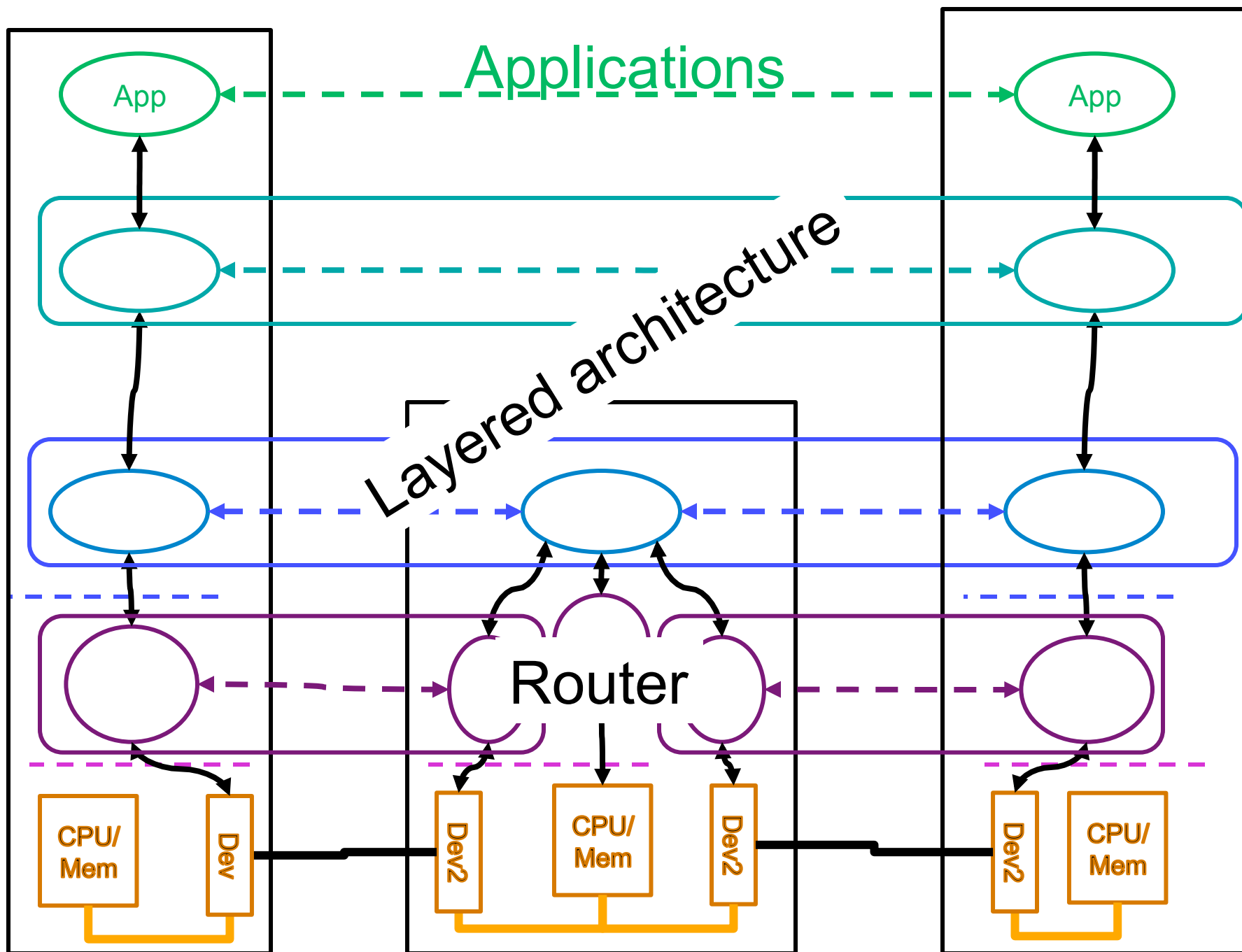
**Find and  
fix bugs?**

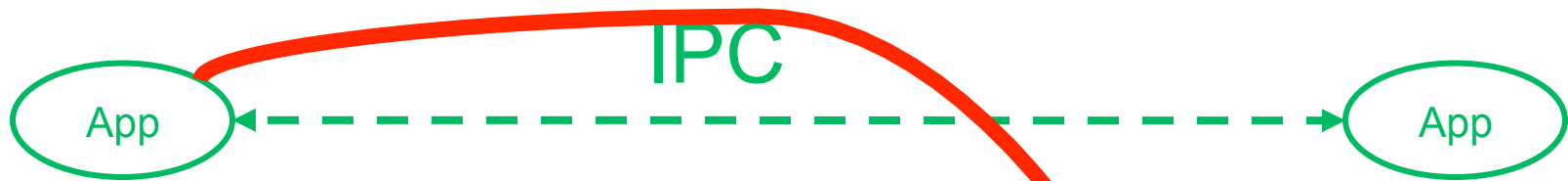


# Patterns in Network Architecture (Day)



- Lots of well-known problems
- Emerging unifying framework
- PNA, RNA (Touch et al), etc
- Compatible with existing theory
- ***Illustrate with simple example***





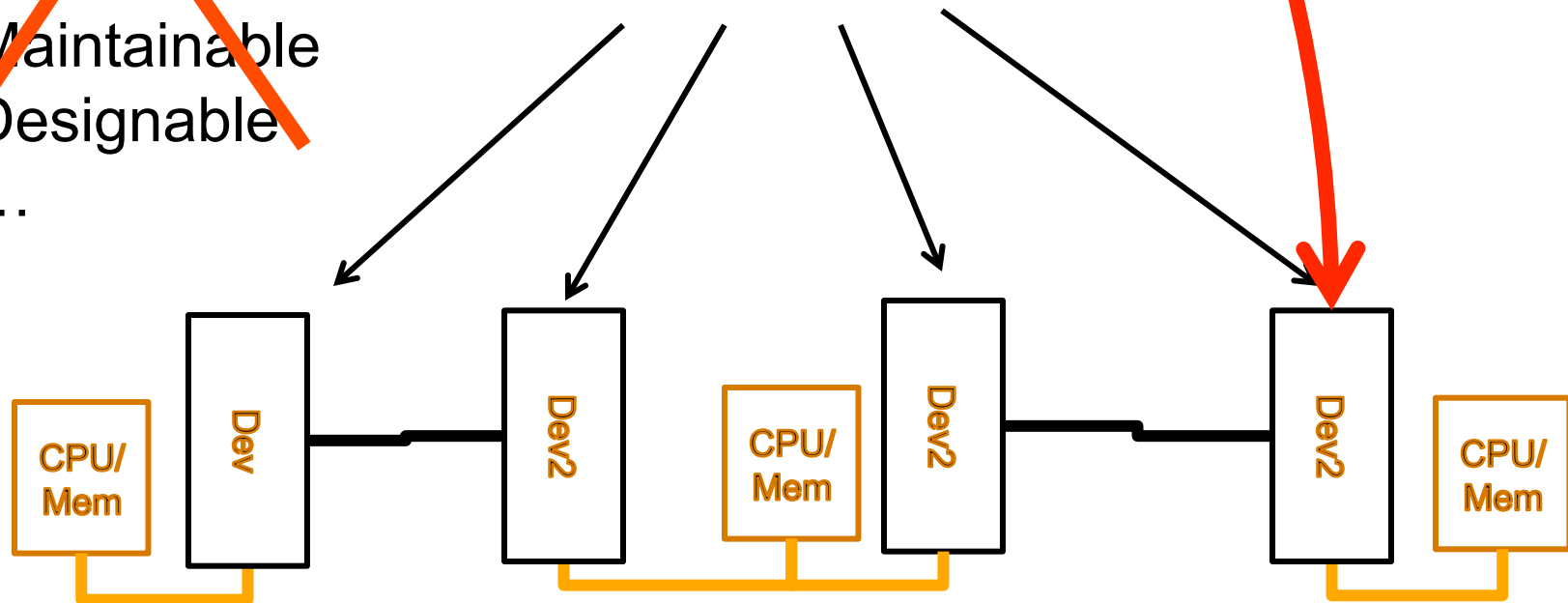
**DNS**

Global  
and direct  
access to  
physical  
address!

~~Robust?~~

- ~~• Secure~~
- ~~• Scalable~~
- ~~• Verifiable~~
- ~~• Evolvable~~
- ~~• Maintainable~~
- ~~• Designable~~
- ~~• ...~~

IP  
addresses  
*interfaces*



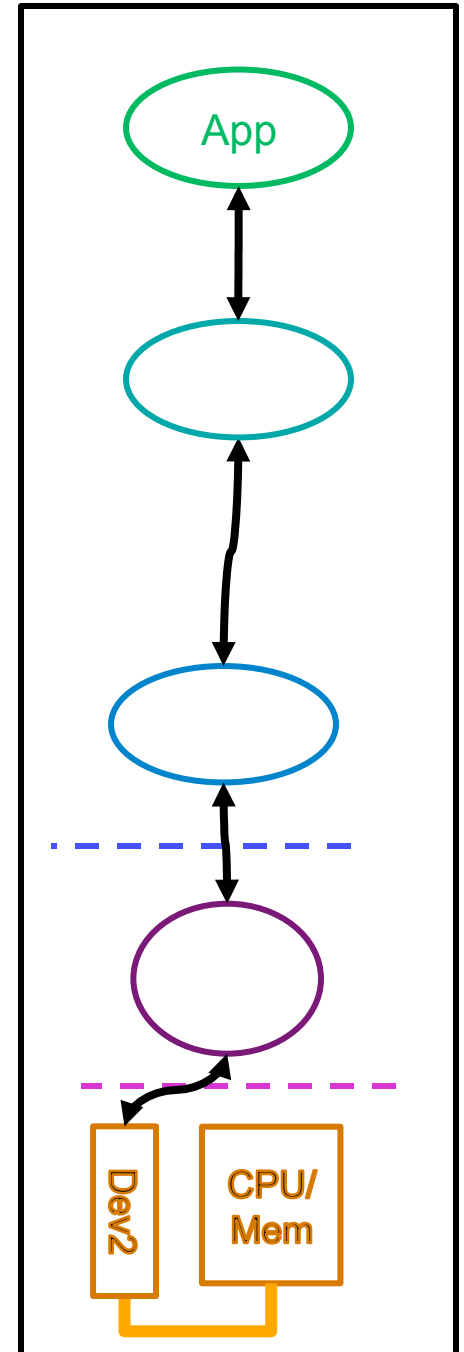
**In operating  
systems:  
Don't cross  
layers**

**Simpler  
example**

**user**

**kernel**

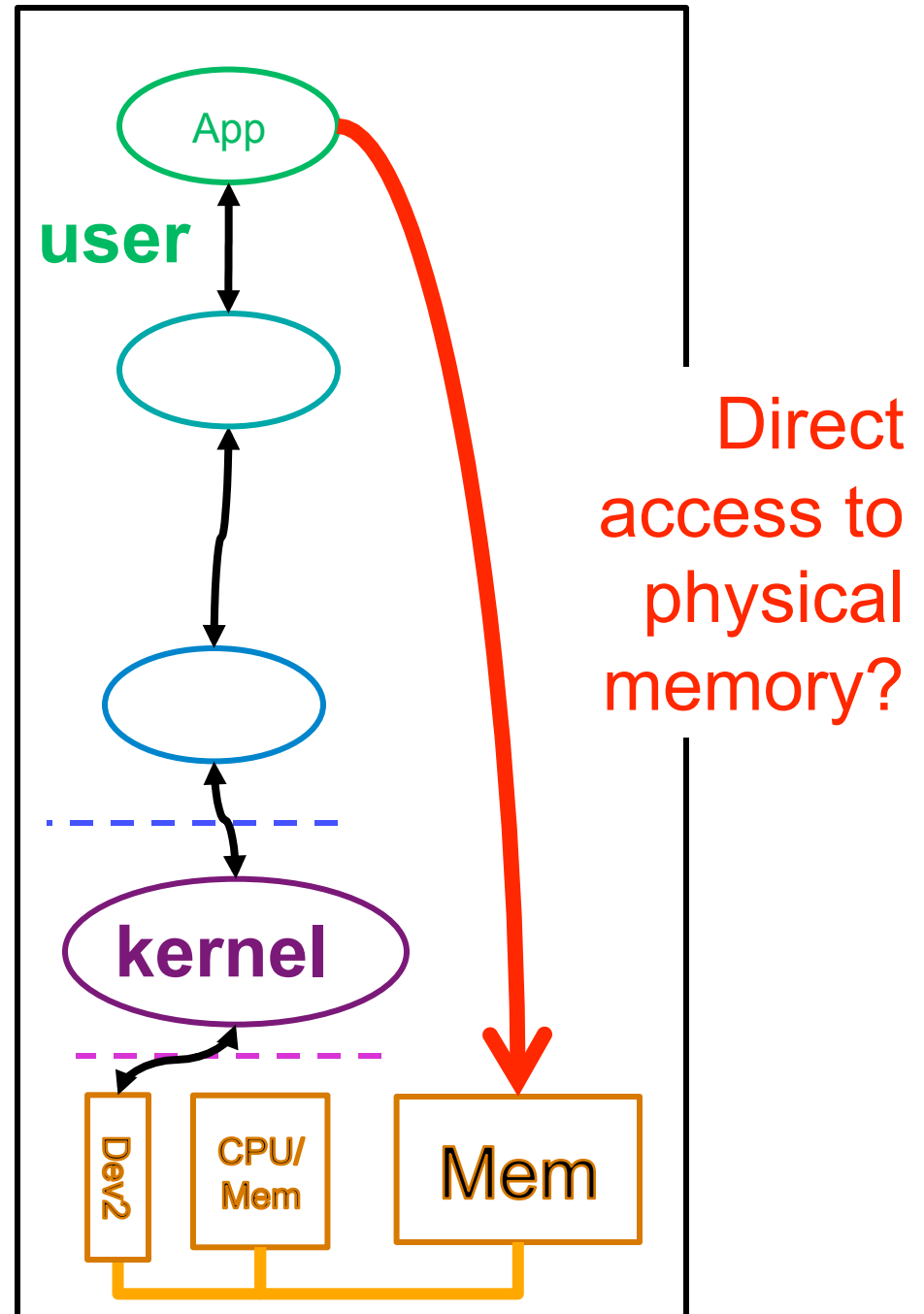
**HW**



# In operating systems: Don't cross layers

~~Robust~~

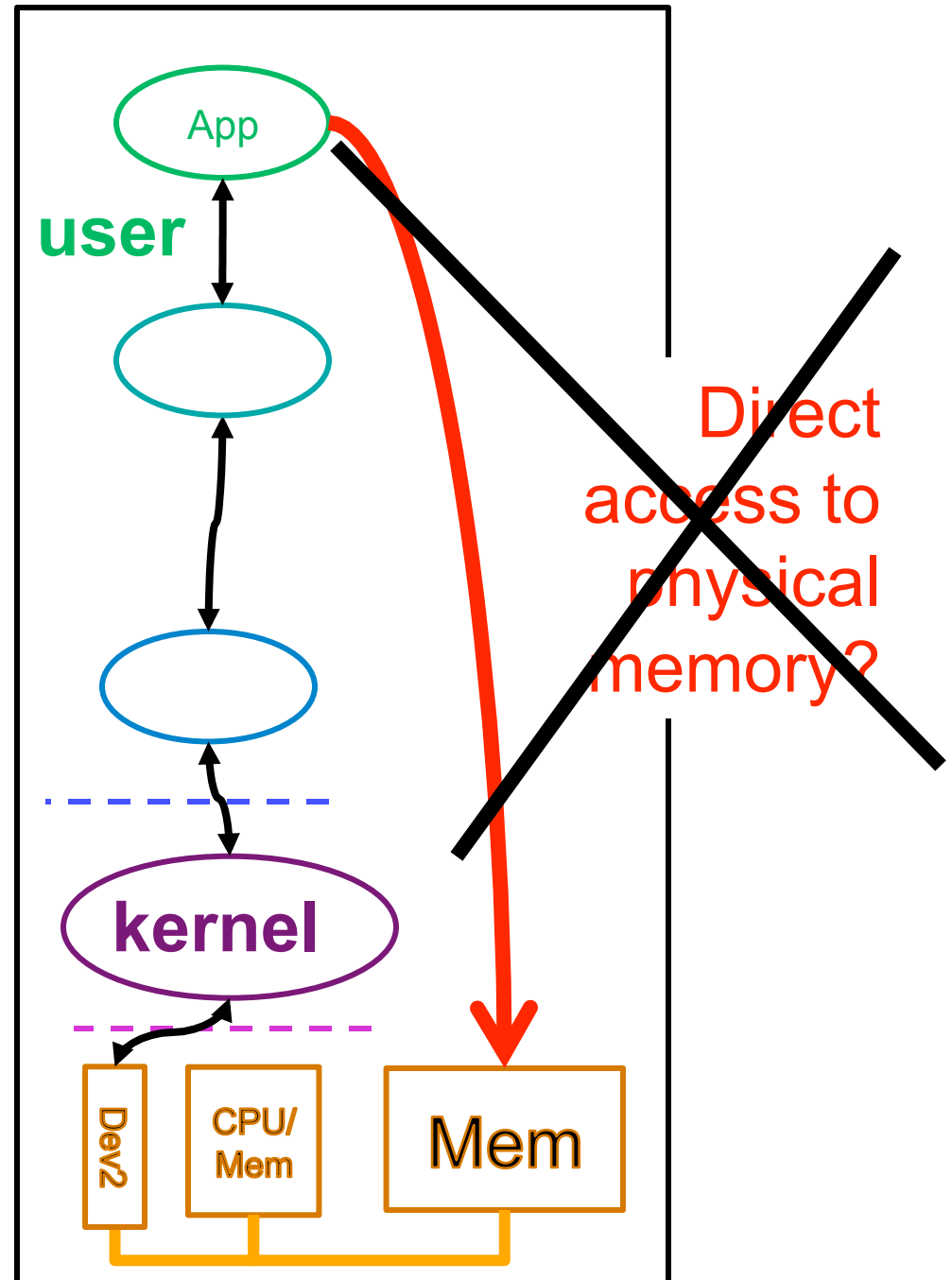
- ~~• Secure~~
- ~~• Scalable~~
- ~~• Verifiable~~
- ~~• Evolvable~~
- ~~• Maintainable~~
- ~~• Designable~~
- ~~• ...~~



**In operating  
systems:  
Don't cross  
layers**

~~Robust~~

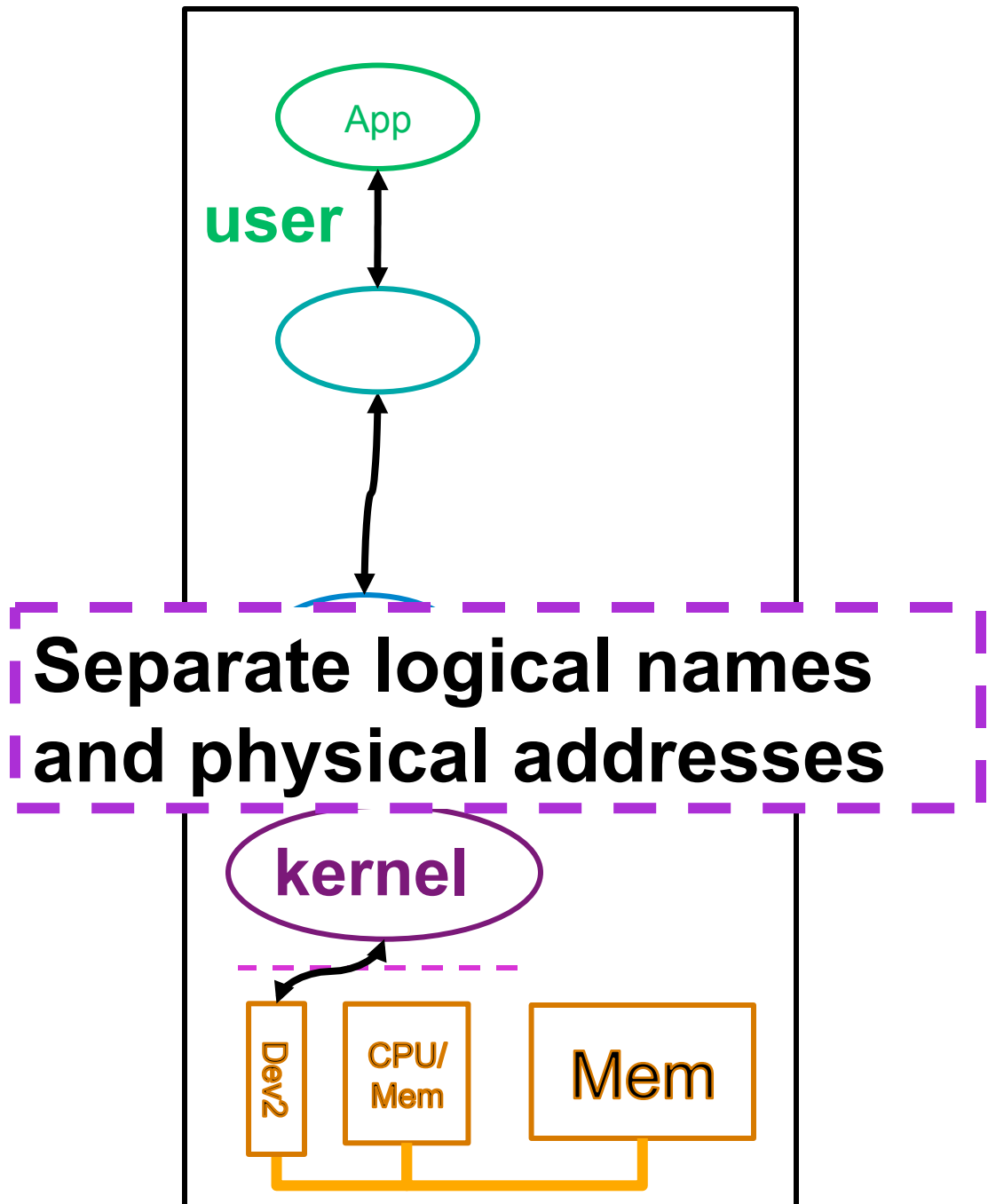
- ~~• Secure~~
- ~~• Scalable~~
- ~~• Verifiable~~
- ~~• Evolvable~~
- ~~• Maintainable~~
- ~~• Designable~~
- ~~• ...~~

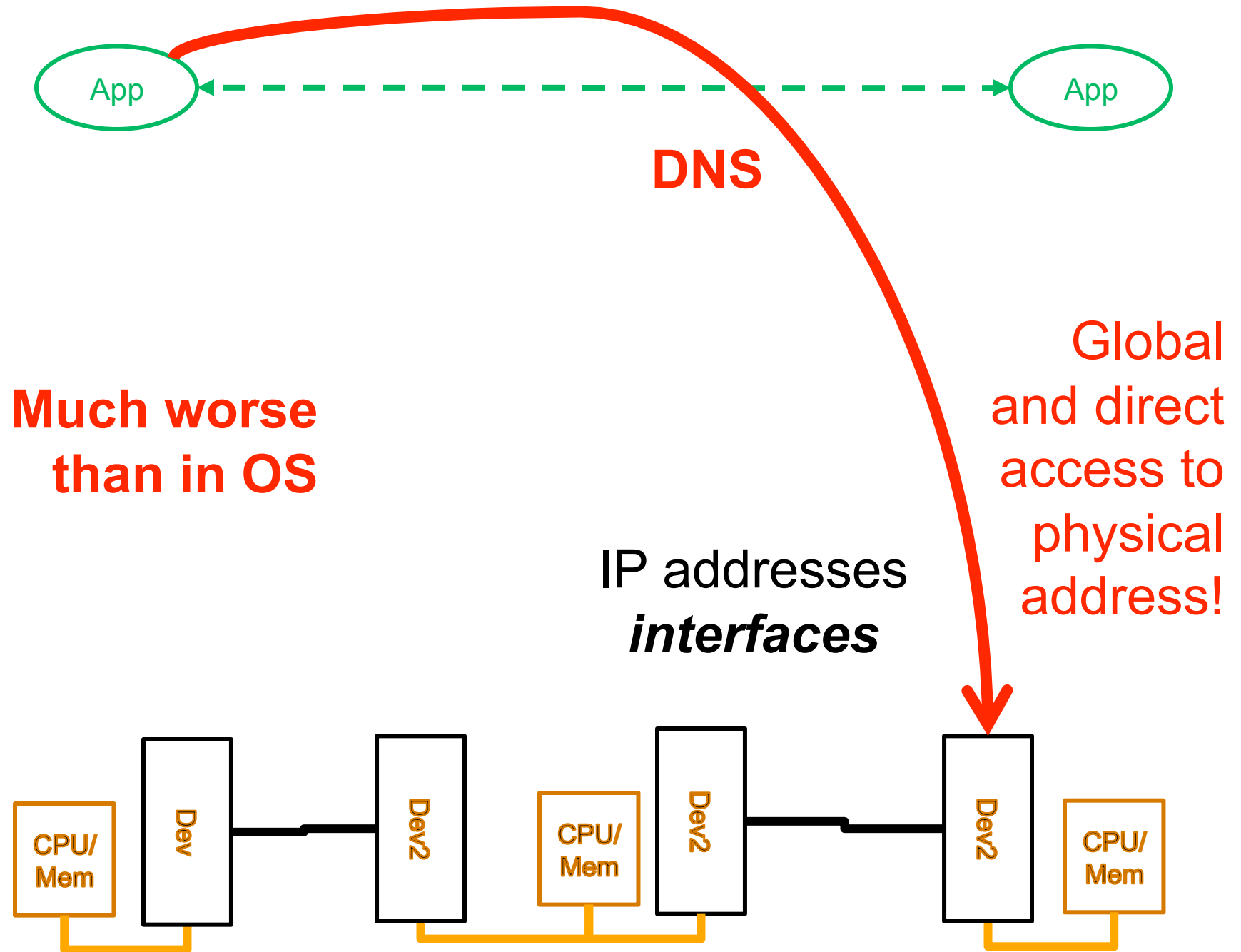


**In operating  
systems:  
Don't cross  
layers (E2E)**

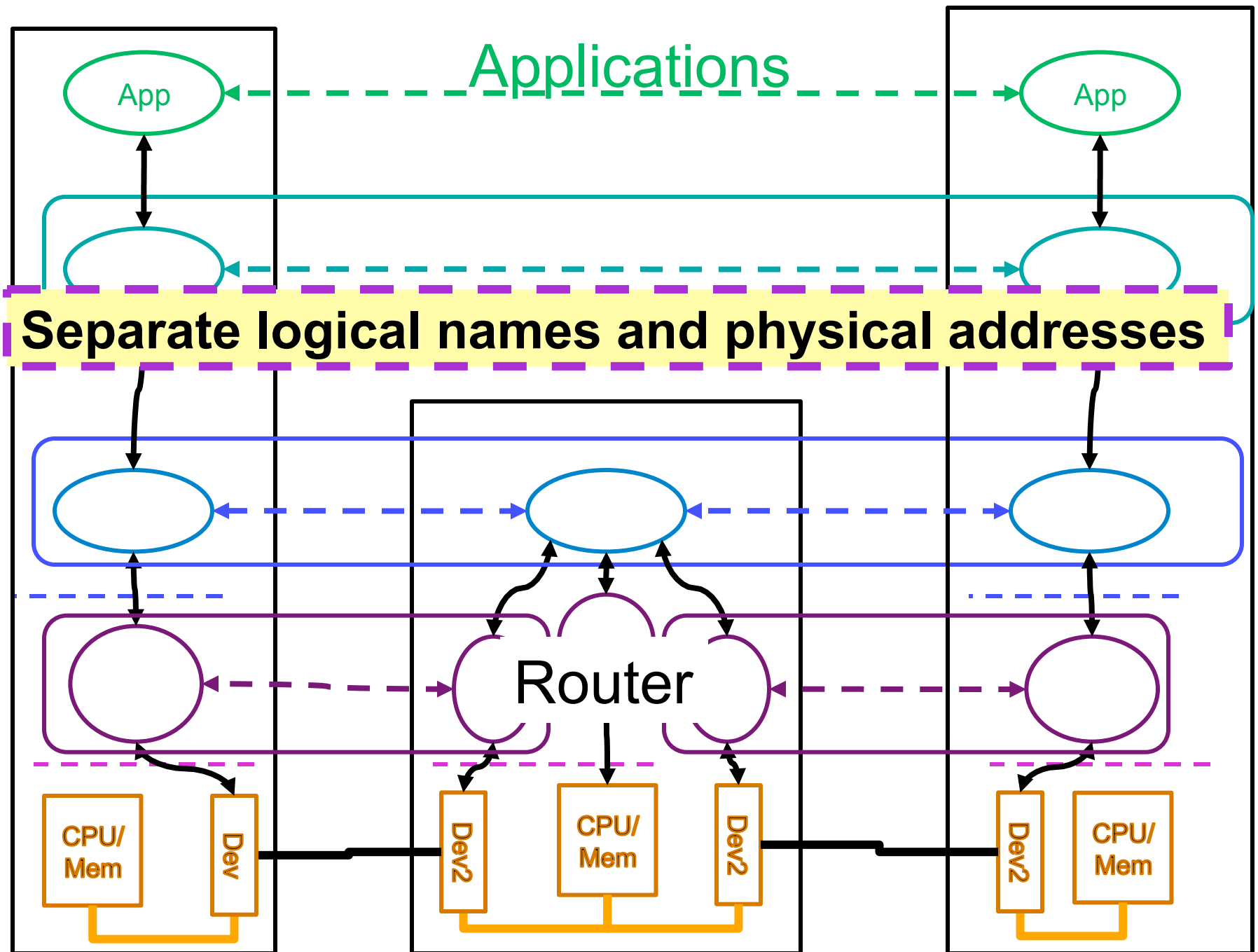
Robust

- Secure
- Scalable
- Verifiable
- Evolvable
- Maintainable
- Designable
- ...





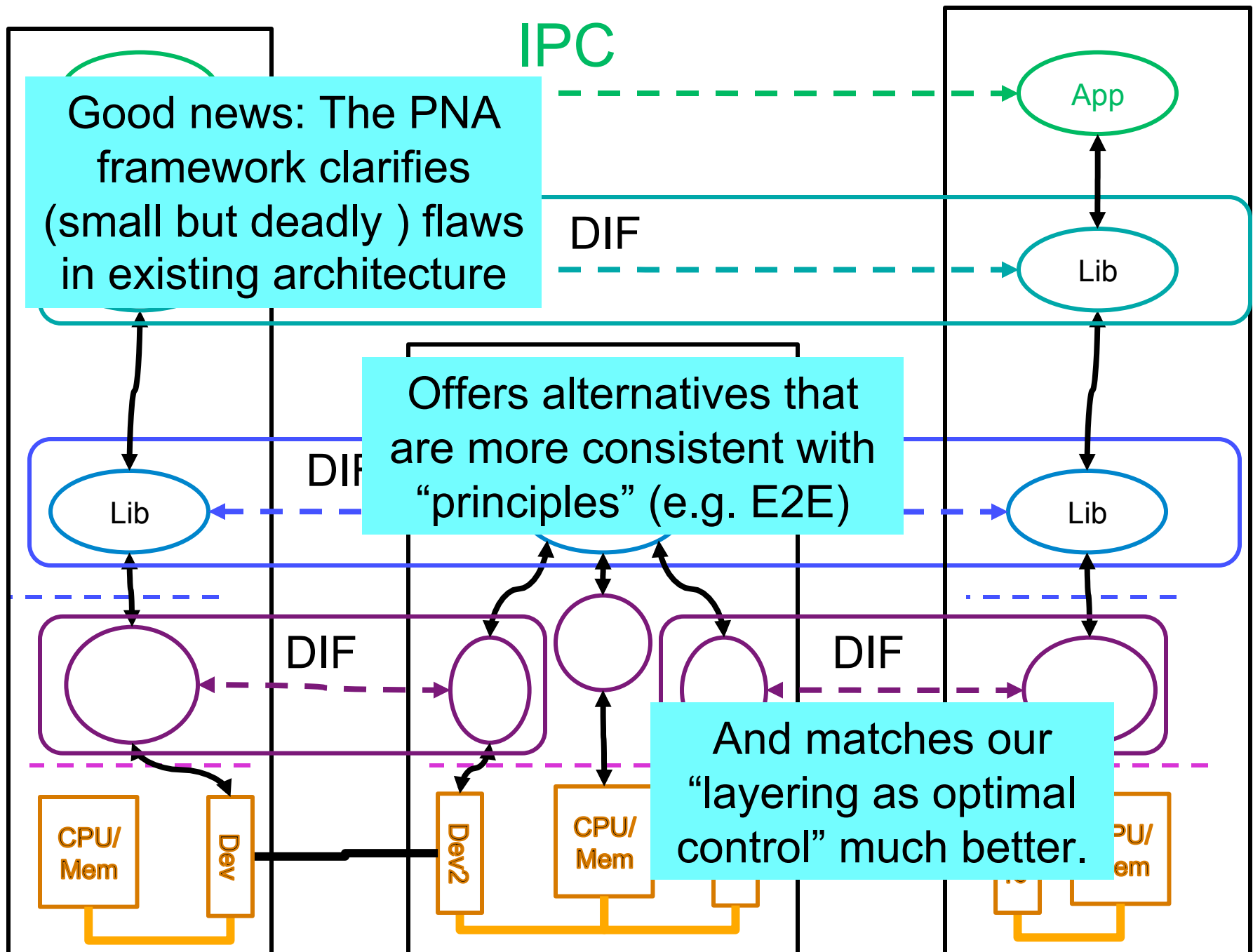


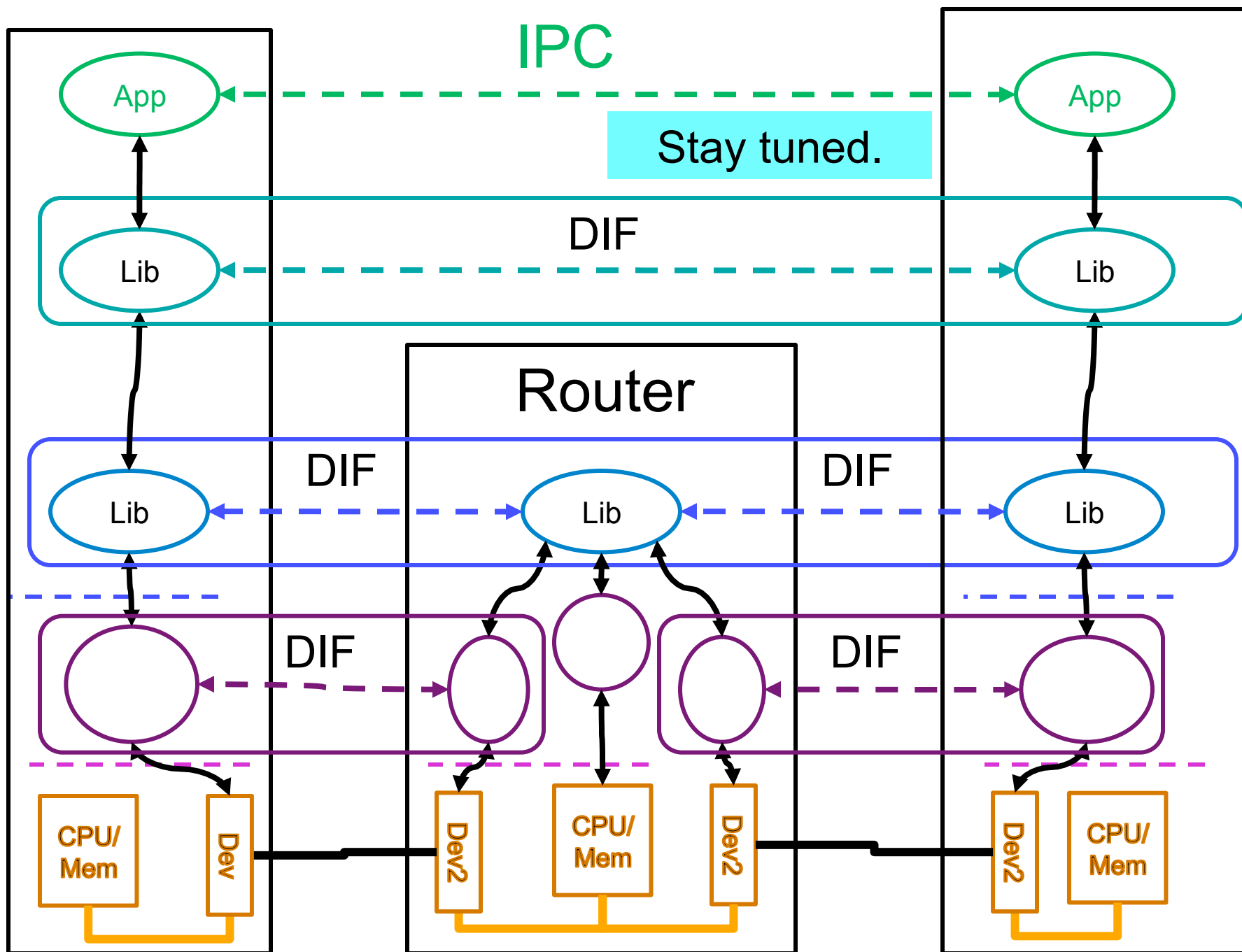


# Other insecurities in TCP/IP?

## Well known attacks

- port-scanning (why “well-known ports”?)
  - connection-opening
  - data-transfer
  - Etc etc
- 
- These are hard to fix in existing architecture
  - Good news is alternatives may be easier than we think

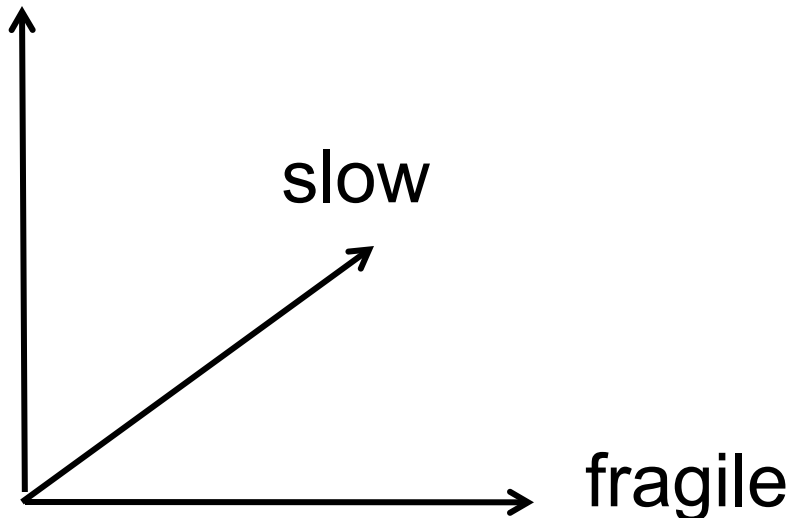




## Naming and addressing

- need to match their layer
- translate/resolve between layers
- not be exposed outside layer
- ***familiar tradeoffs here***

wasteful



## Tradeoffs

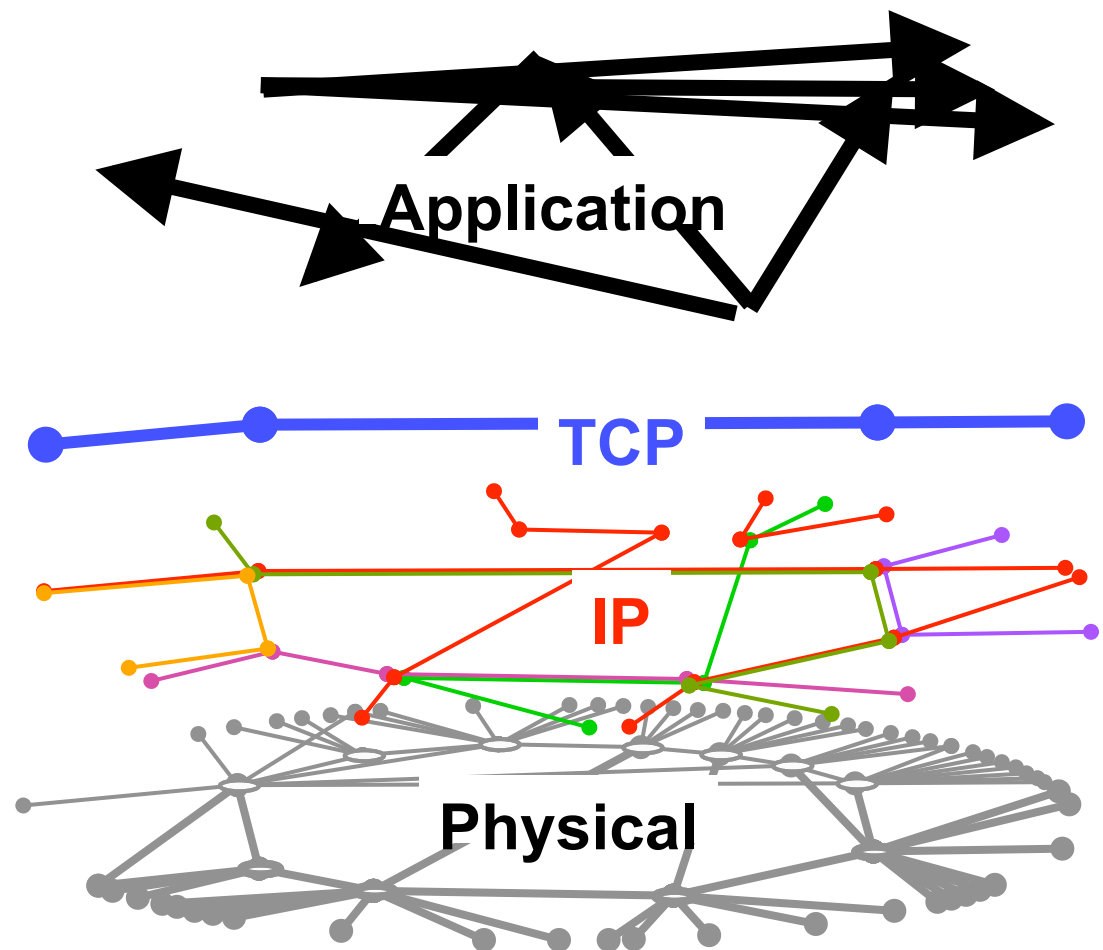
- Addressing complexity
- Table sizes
- Forwarding
- Optimal routes
- Table updates

## Naming and addressing

- need to match their layer
- translate/resolve between layers
- not be exposed outside layer

## Architecture issues

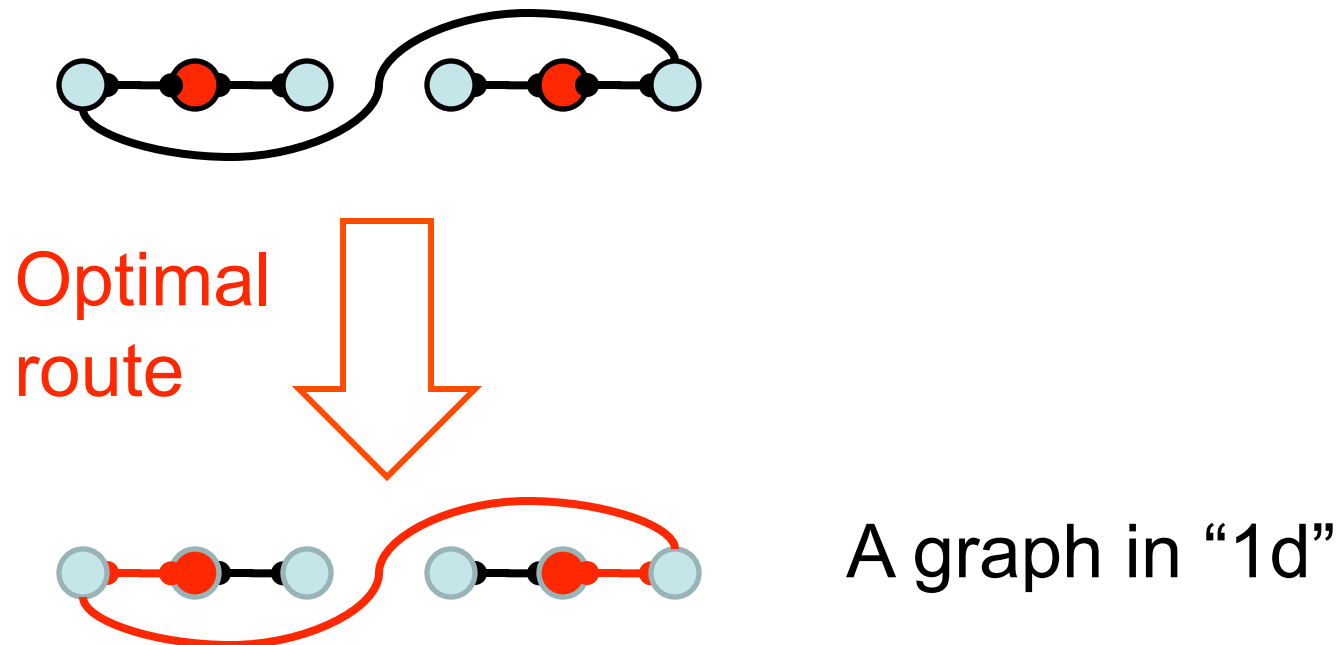
- DNS
- NATS
- Firewalls
- Multihoming
- Mobility
- Routing table size
- Overlays
- ...

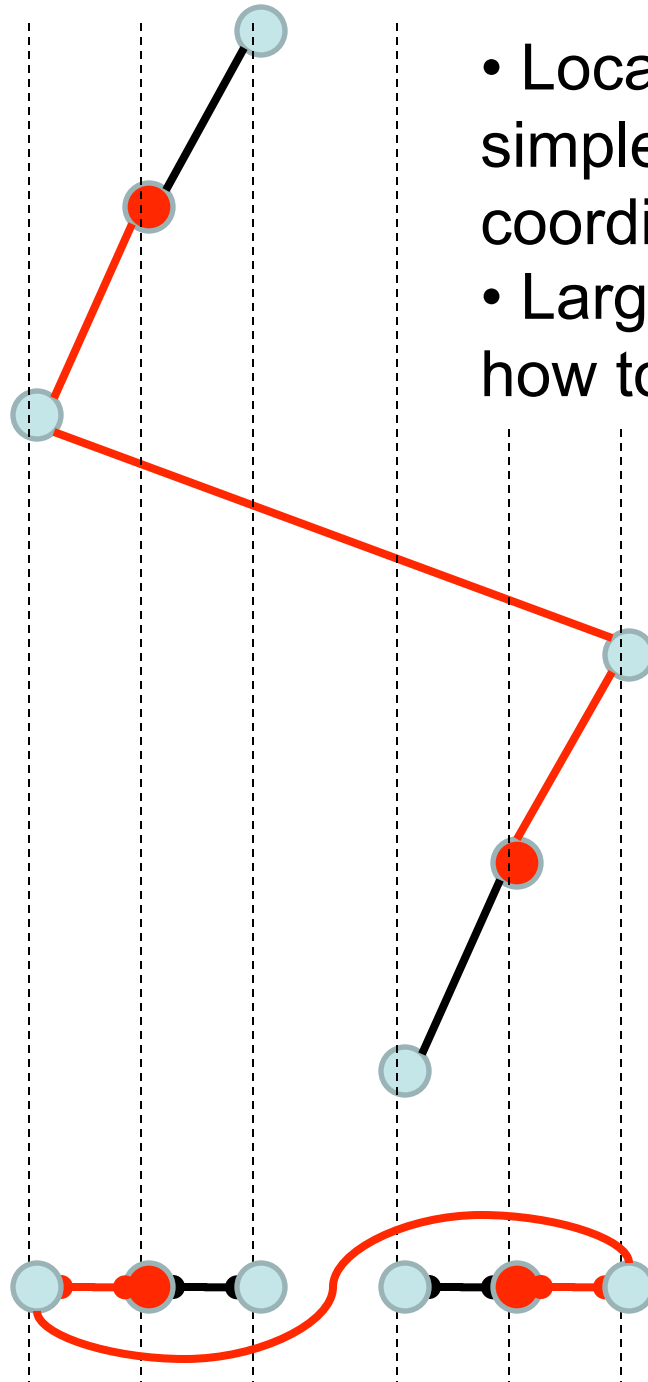


# Trivial toy example

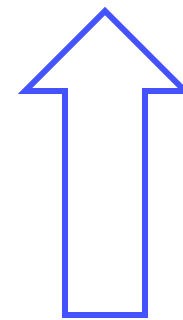
Consider a 1 dimensional geography

- Assume some link connectivity
- Optimal route might be indirect
- Consider route between red nodes



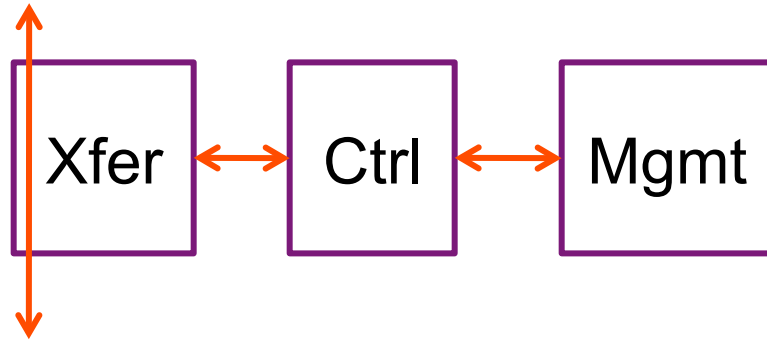


- Local, greedy routing using simple norms and “virtual coordinates” is globally optimal
- Large and growing literature on how to do this systematically



Add a virtual dimension





## Universal functions?

- Transfer or transform (fastest)
  - Domain specific (data, power, goods, etc)
  - Depends on demand and supply of resources
- Control (middle)
  - Schedule/MUX resources in time and space
  - Flow and error control
- Management (slowest)
  - **What** resources are available?
  - **Where** are they?
  - Cost? Risk? etc

Domain specific, local

Xfer

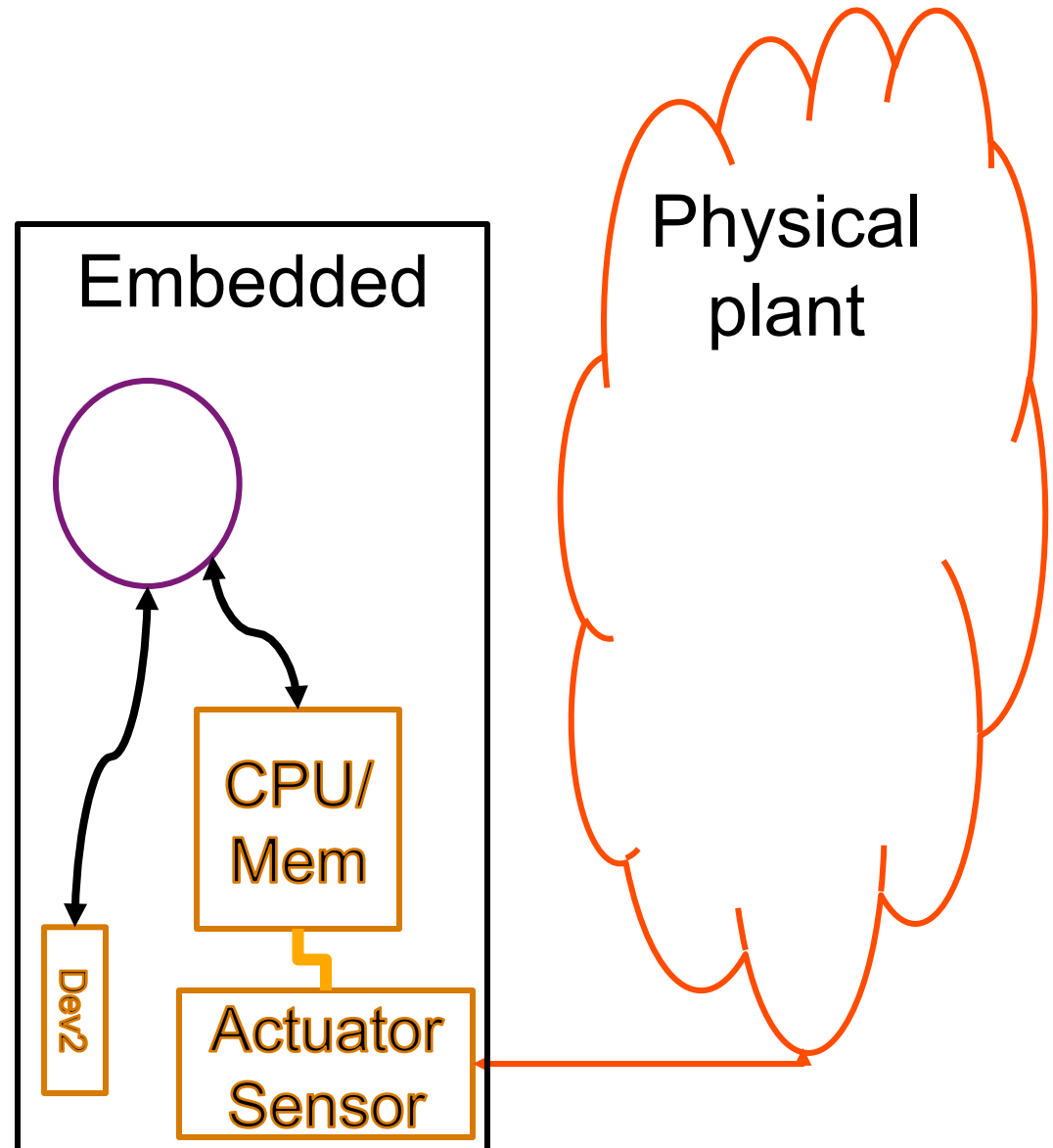
Ctrl

Mgmt

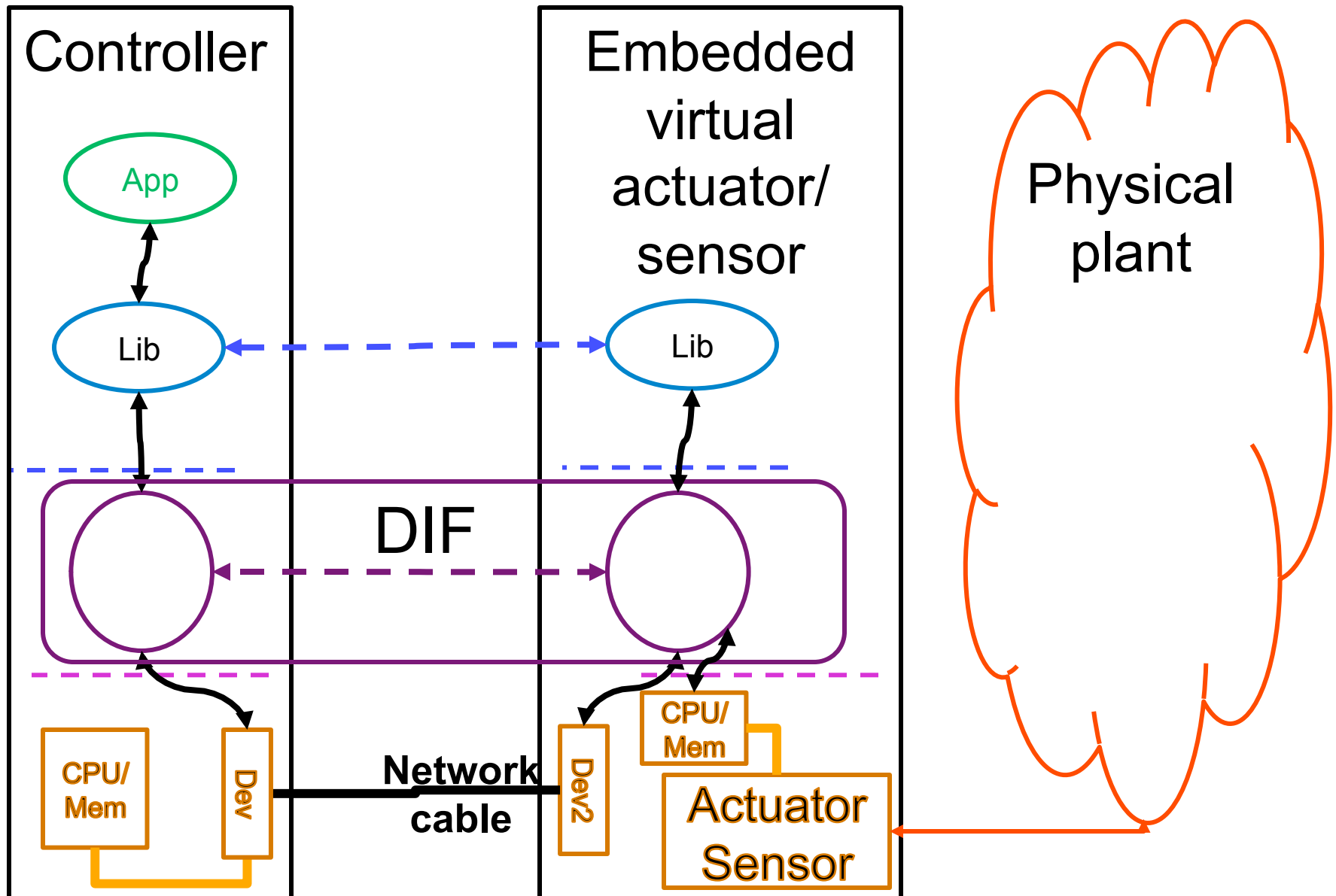
**Network,  
universal?**

- Ctrl and Mgmt just aspects of a single problem on different time scales
- The distinction may be somewhat artificial and domain specific
- Ctrl/Mgmt in NetME:
  - More complex as the “Net” part grows
  - Will be our focus/goal of a unified theory
  - From physics to information to computation to control

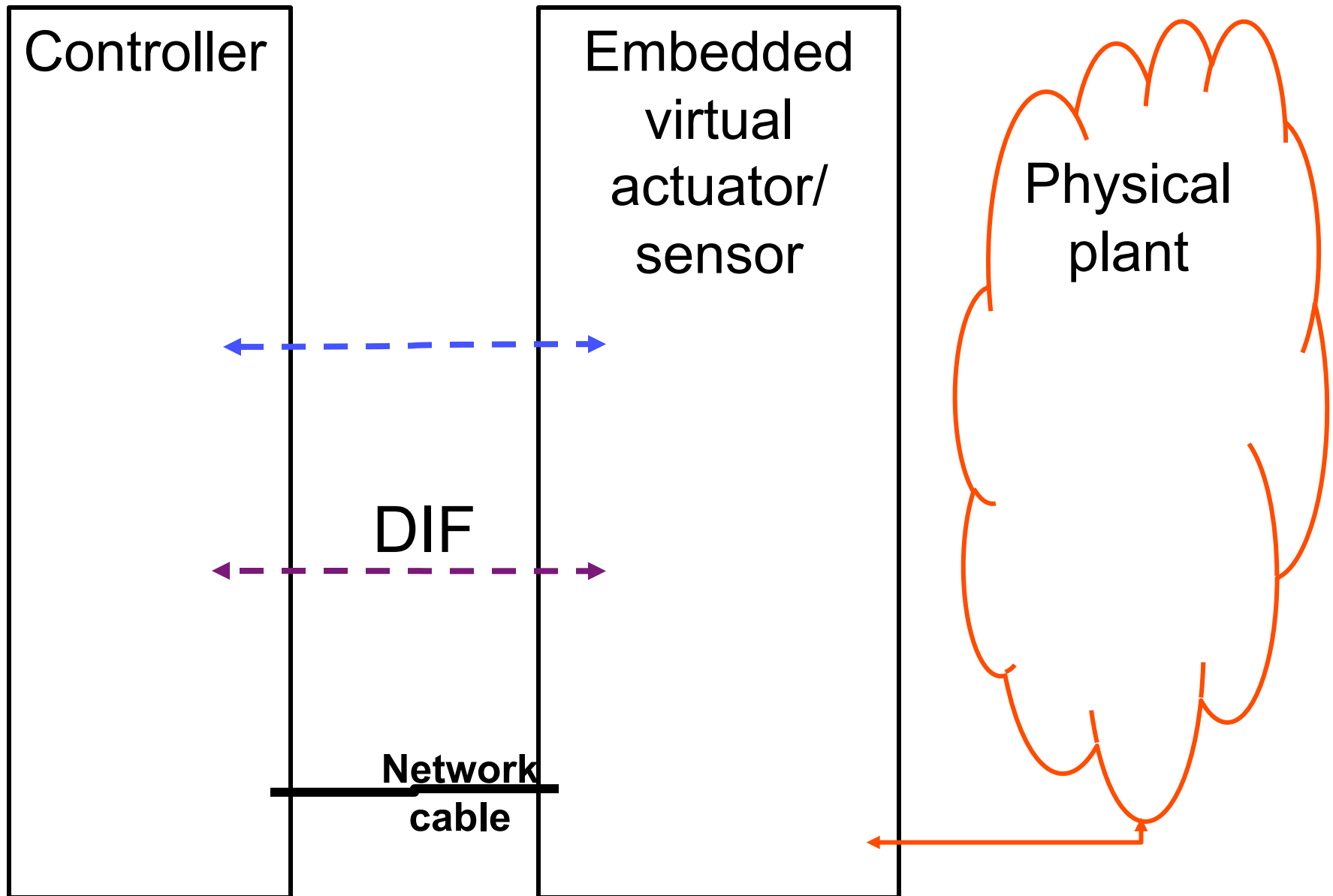
# Embedded



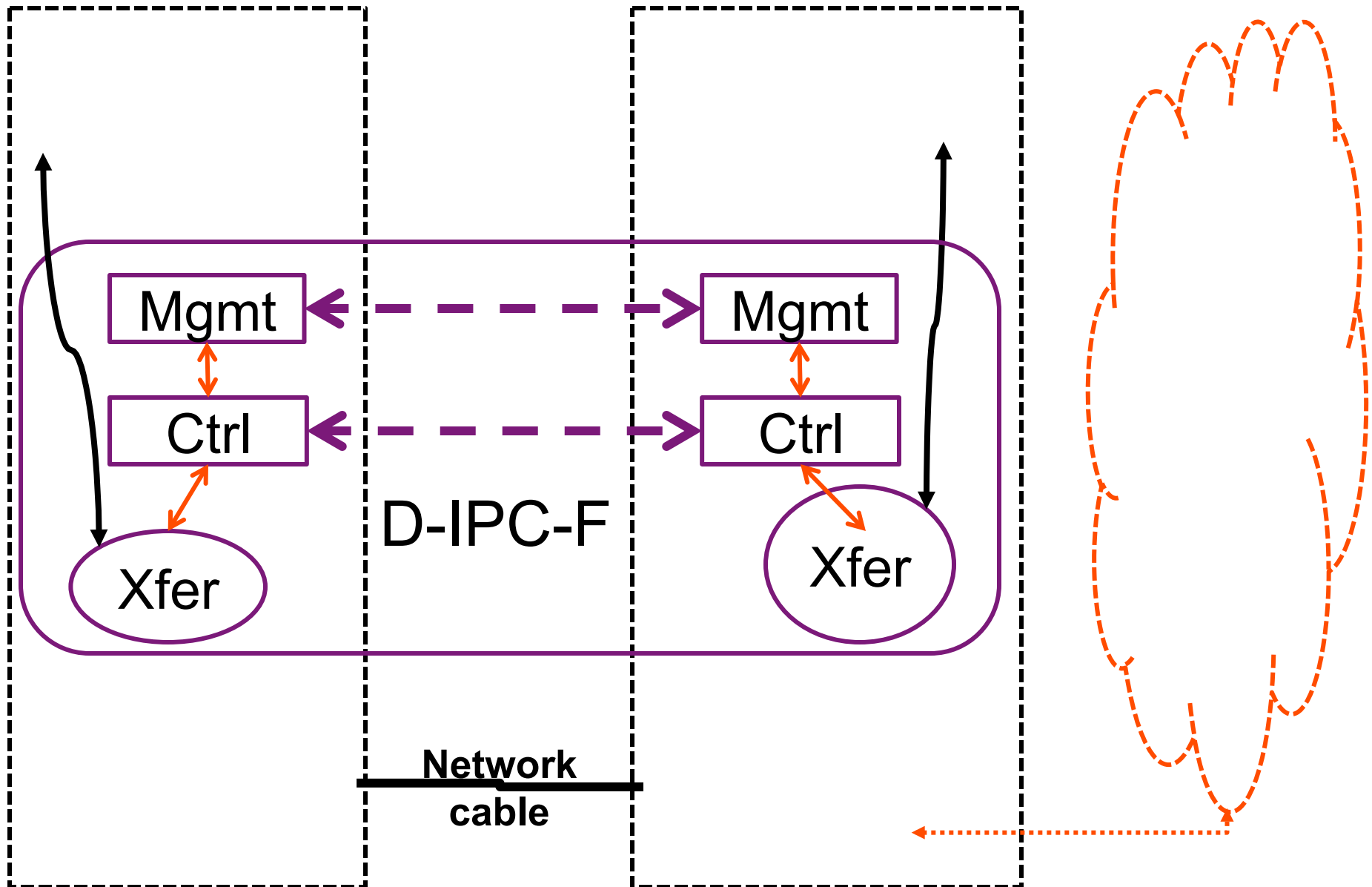
# Networked embedded



# Meta-layering of cyber-phys control

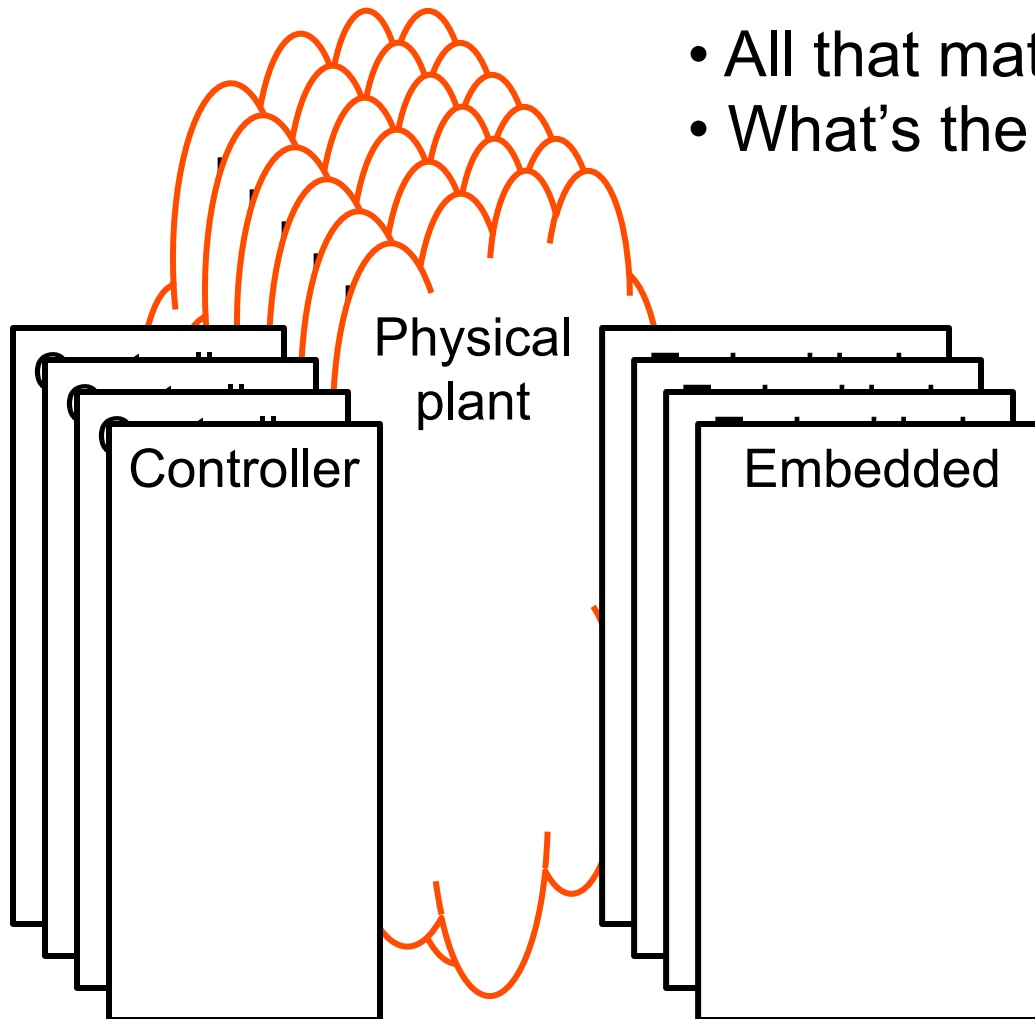


## Micro-layering of D-IPC-F

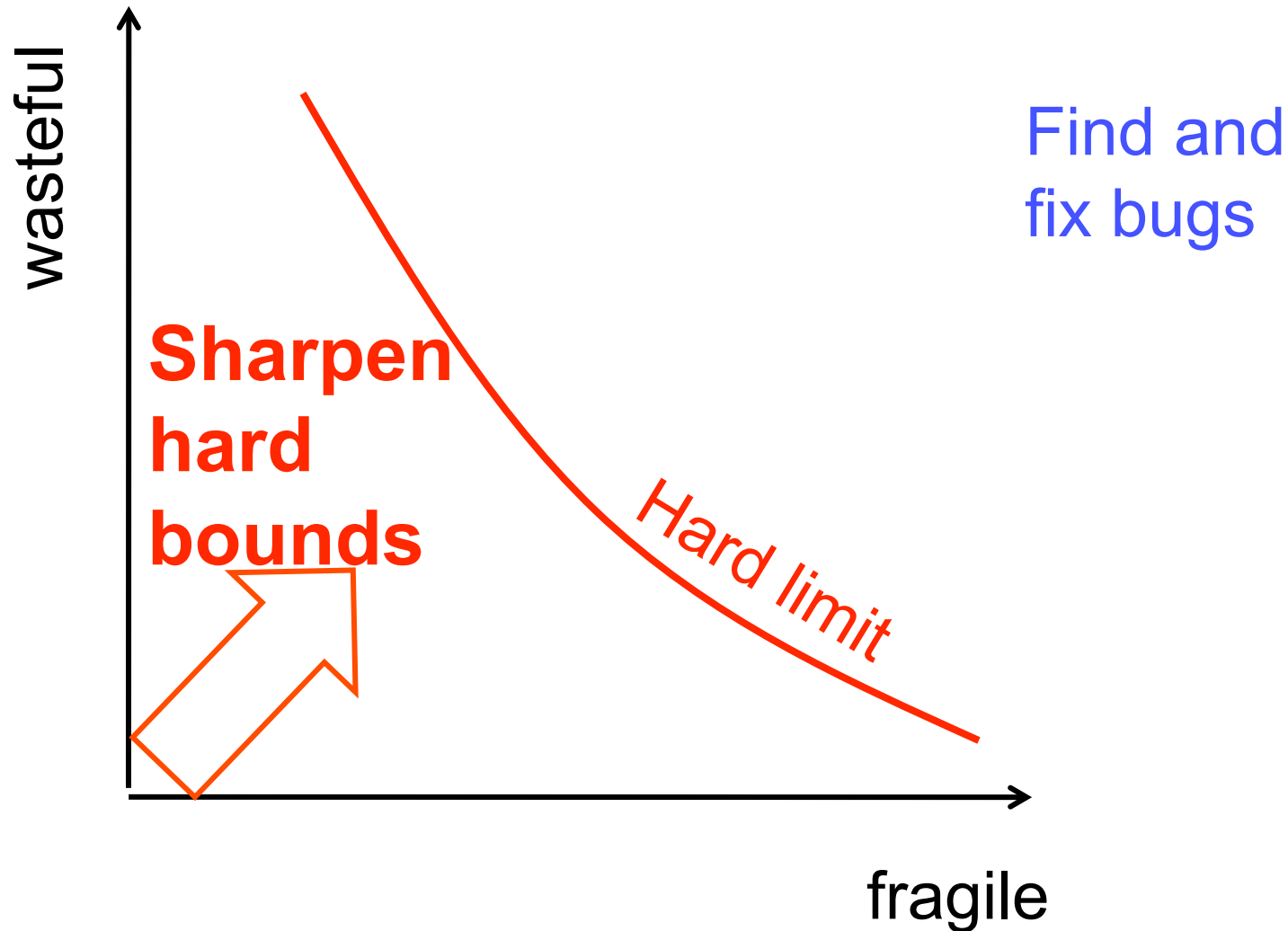


# Smartgrid and cyberphys

- Everything is networked.
- Flows of data and power.
- All that matters is ***action***.
- What's the right architecture?



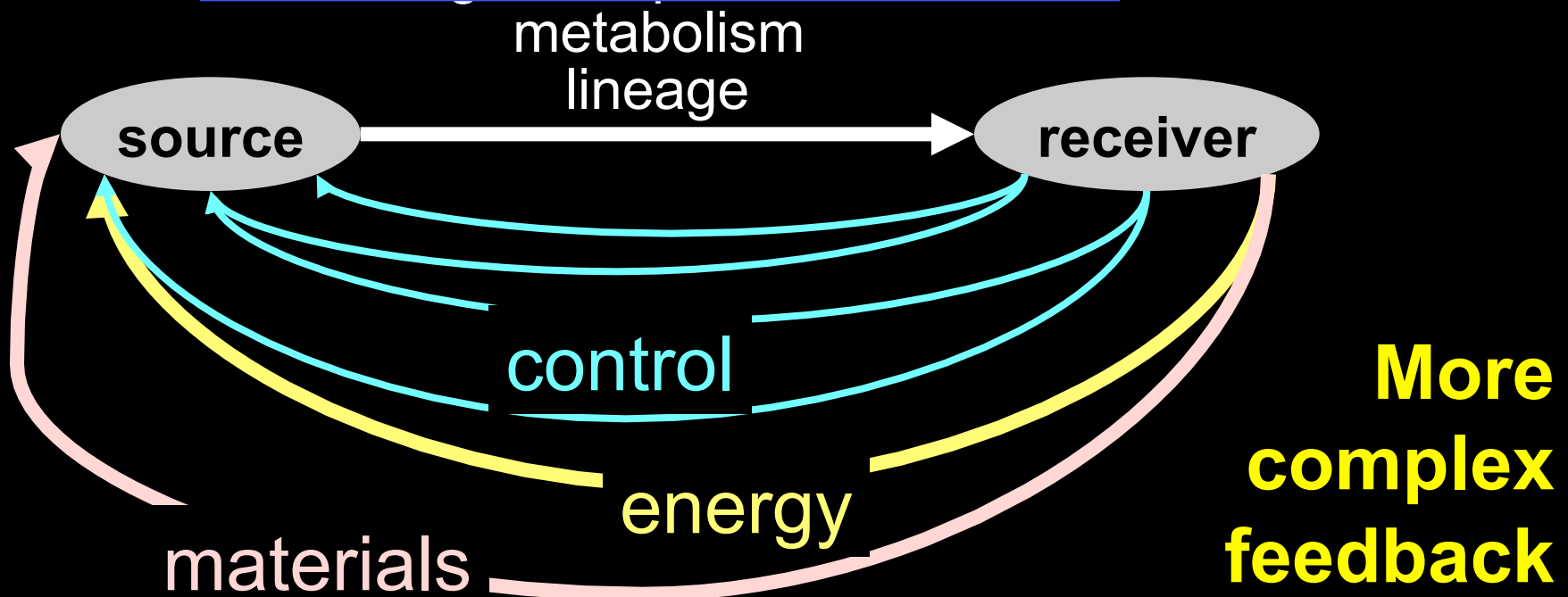
# Complementary approaches





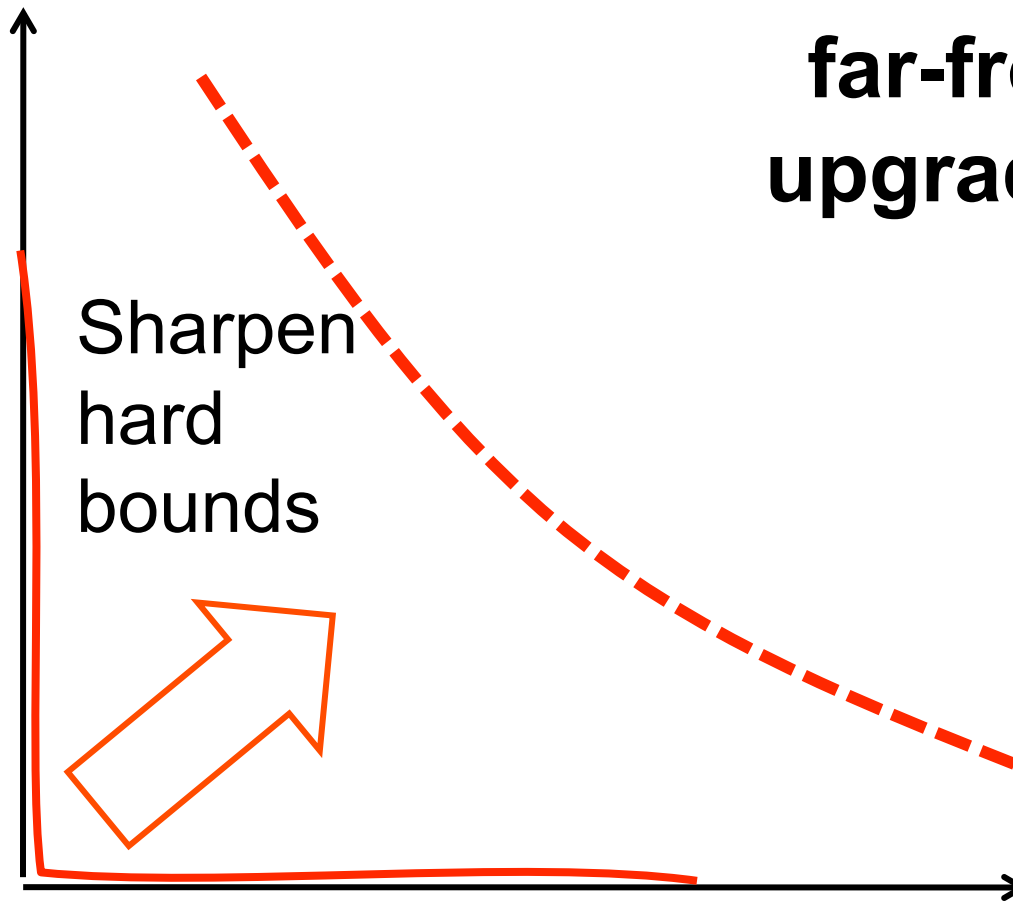
Previously: Hard tradeoffs between control and metabolic efficiency  
New: more mechanistic details for “efficiency” in control context

$$\frac{1}{\pi} \int_0^{\infty} \ln |S(j\omega)| \frac{z}{z^2 + \omega^2} d\omega \geq \ln \left| \frac{z+p}{z-p} \right|$$



## Example

**slow**

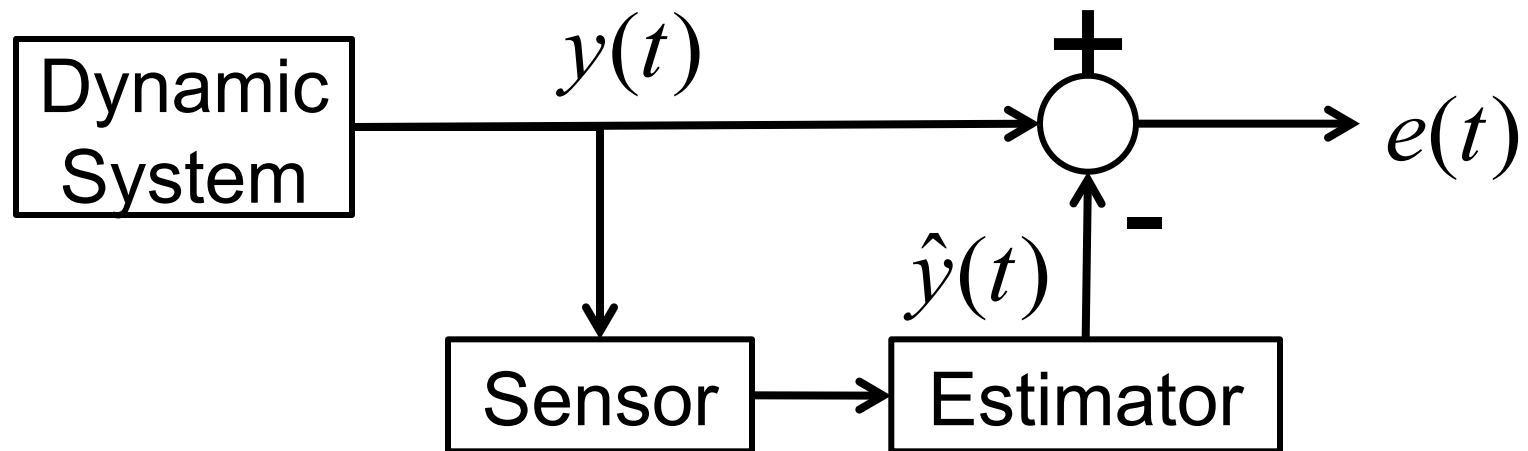


Sharpen  
hard  
bounds

**A transient and  
far-from-equilibrium  
upgrade of statistical  
mechanics**

**error**

# Estimation

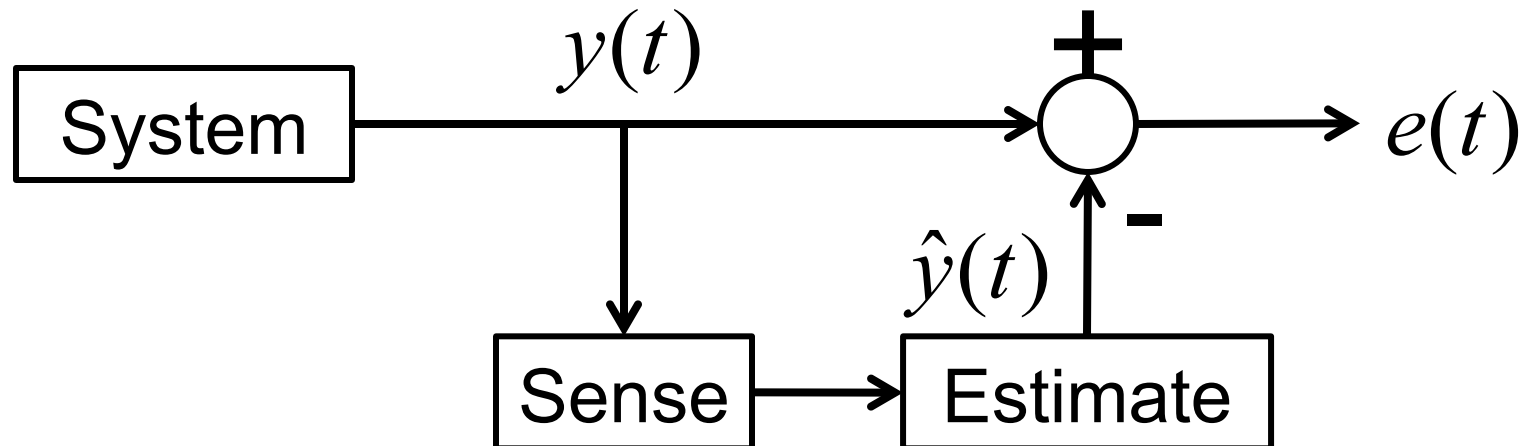


**Ideally**  $E(e^2(t)) \approx 0$

# Estimation

Ideally

$$E(e^2(t)) \approx 0$$



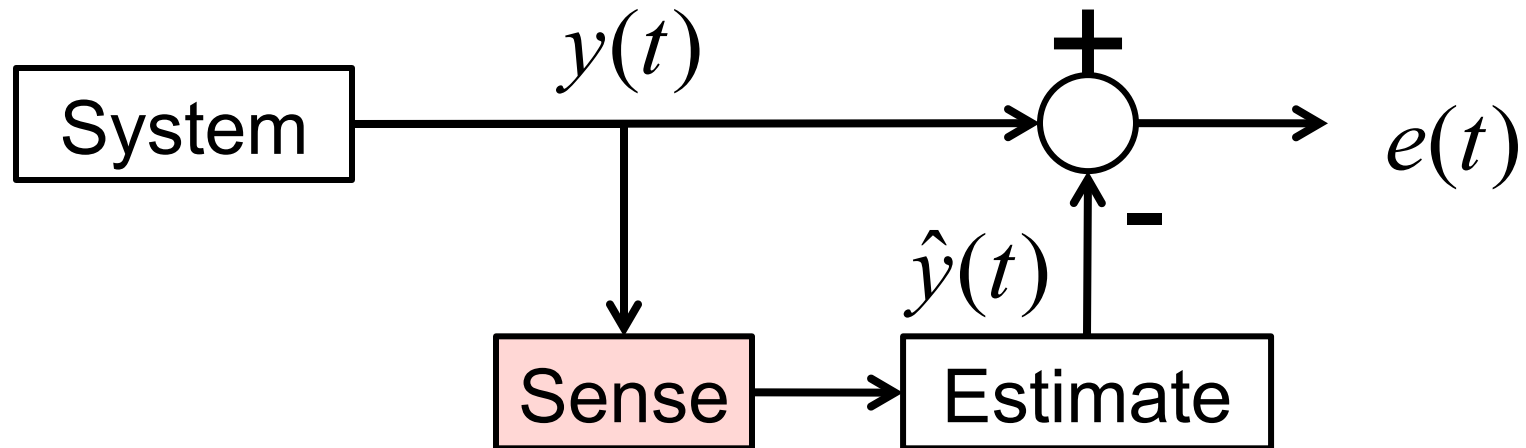
**Realistically:**

- Sensor “noise”
- Back action

Why? What are the consequences?

- Focus on fast transients (speed versus error).
- Asymptotic equilibrium same as standard physics.

# Sensor “noise” assumptions



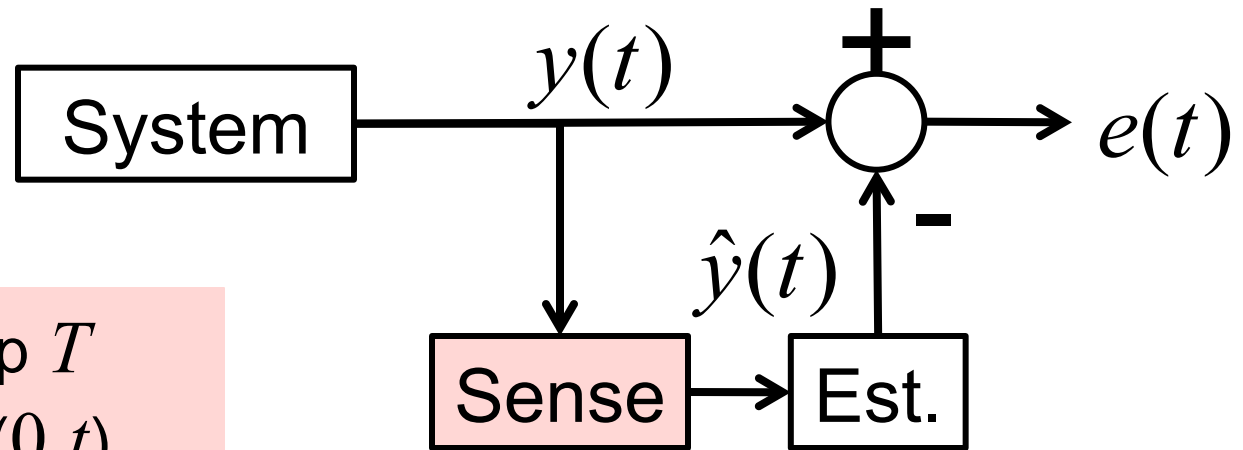
Sensor physics (phenomenology):

- Micro: many degrees of freedom
- Micro: energy conserving
- $\Rightarrow$  Macro: heat  $kT$  at temperature  $T$ , and noise

Use CDS tools to rigorously capture transients and nonequilibrium dynamics

## Sensor “noise”

- Sensor at temp  $T$
- Short interval  $(0, t)$

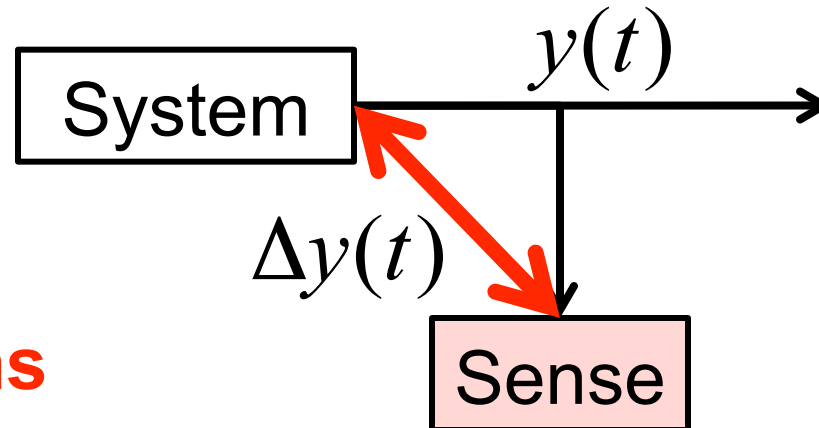


Optimal estimator has hard limit

$$E(e^2(t)) \propto \frac{kT}{t} + O(1)$$

- Boltzmann constant  $k$
- Units-dependent constants not shown, important in practice
- Asymptotic equilibrium recovers standard stat mech theory

**Back  
action  
assumptions**



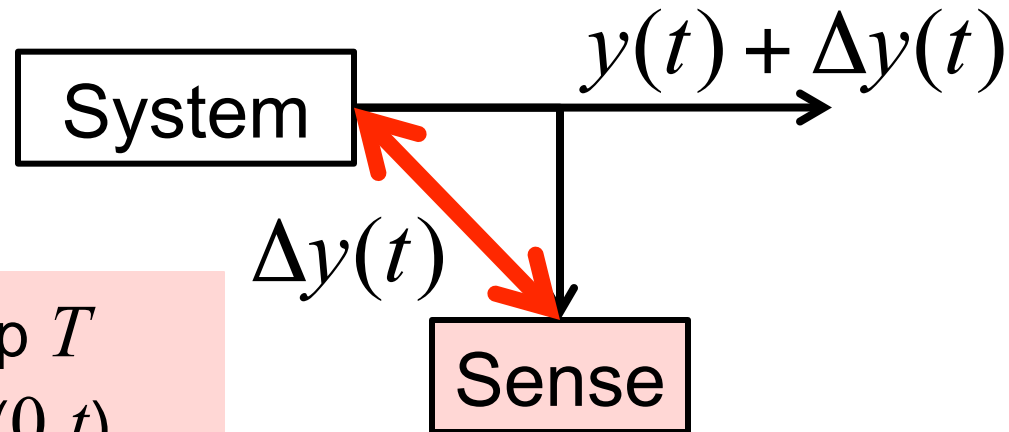
Sensor physics (phenomenology):

- Micro: entire system energy conserving
- $\Rightarrow$  Macro: nontrivial impedance in sensor
- Note: this occurs even classically, and even if sensor has infinite energy supply (assume for now)

Use CDS tools to rigorously capture transients and nonequilibrium dynamics

## Back action

- Sensor at temp  $T$
- Short interval  $(0, t)$

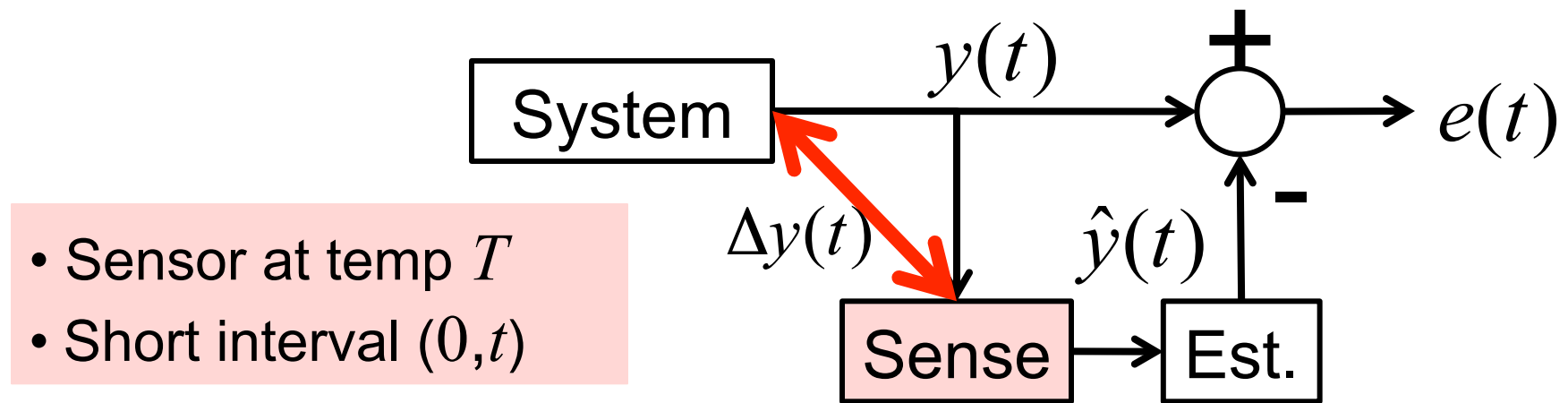


Minimal back action has hard limit

$$E\left(\Delta y^2(t)\right) \propto kTt + O\left(t^2\right)$$

- Units-dependent constants not shown, important in practice
- Asymptotic equilibrium recovers standard stat mech theory





- Sensor at temp  $T$
- Short interval  $(0, t)$

$$E\left(\Delta y^2(t)\right) \geq kTt + O(t^2)$$

Back action

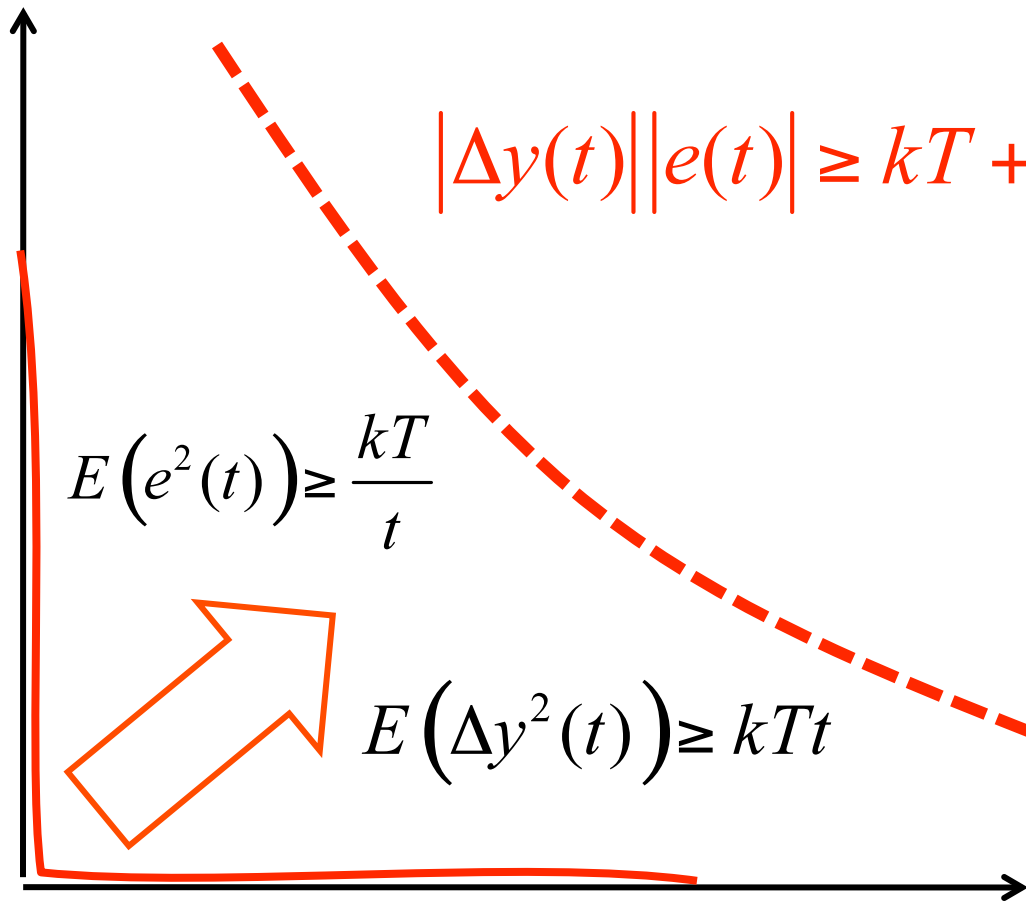
$$E\left(e^2(t)\right) \geq \frac{kT}{t} + O(1)$$

Sensor "noise"

- Simplest hard tradeoffs on speed and errors
- More tradeoffs (e.g. energy overhead vs speed vs errors)
- Just scratching the surface
- Actuators, computation, quantum effects,...?
- Aside: linear active elements need nonlinear implementation

A transient and far-from-equilibrium  
upgrade of statistical mechanics

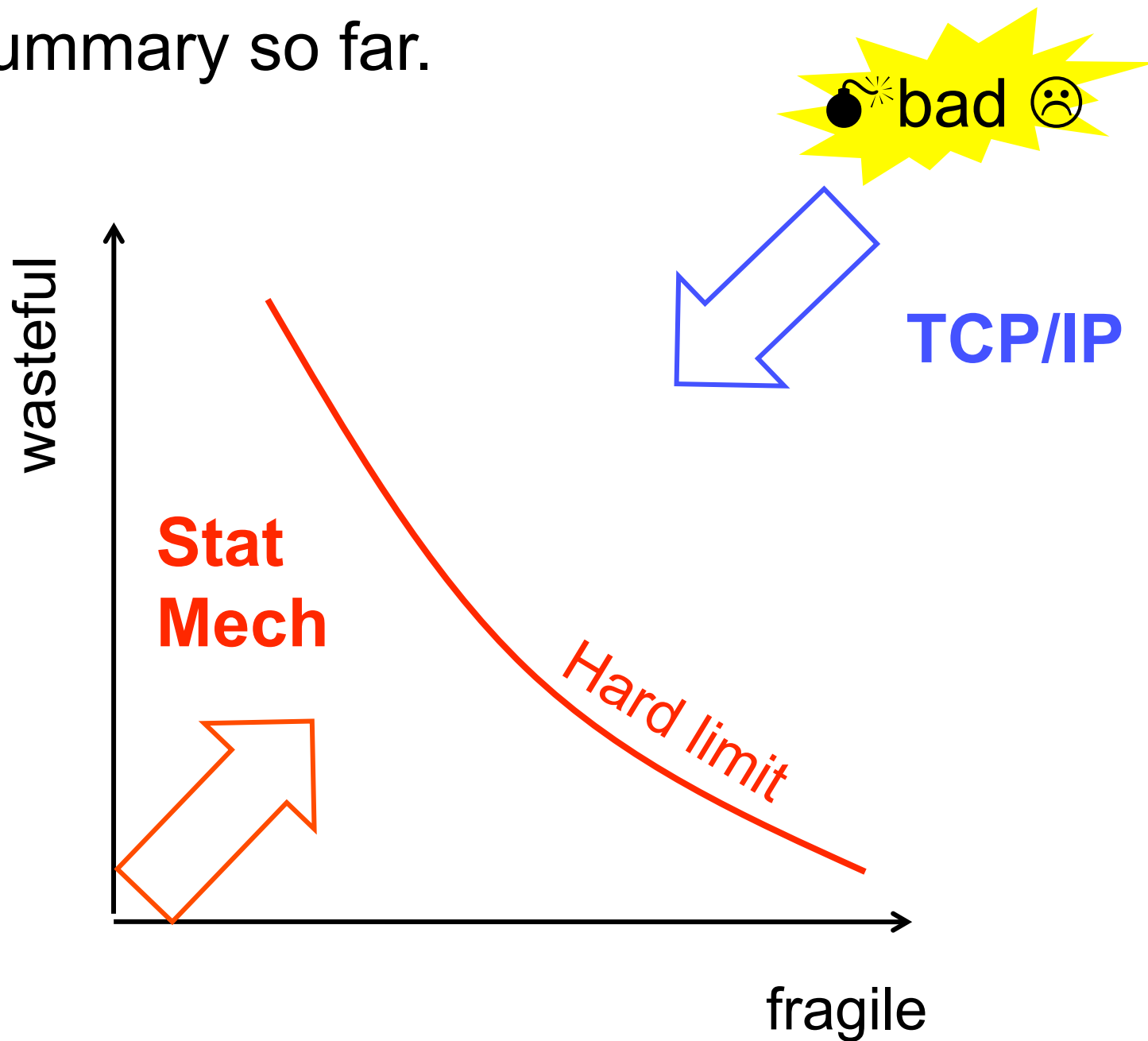
**slow**



Cold sensors are  
better and faster  
(but not cheaper)

**error**

Summary so far.



Conjecture: Cells and  
brains are RYF but not  
gratuitously fragile

